

Click here to ask an associate for production status of specific part numbers.

General Description

The Himalaya series of voltage regulator ICs, power modules, and chargers enable cooler, smaller, and simpler power supply solutions. The MAX17703 is a high-efficiency, high-voltage, synchronous, step-down, Himalaya Lion battery-charger controller designed to operate over an input-voltage range of a 4.5V to 60V. The MAX17703 operates over a wide -40°C to +125°C temperature range and offers a complete charging solution for Li-ion batteries with a ±4% accurate constant current. The output voltage is programmable from 1.25V up to (V_{DCIN} - 2.1V) with ±1% regulation accuracy.

The device uses an external nMOSFET to provide input supply-side short-circuit protection, preventing battery discharge.

The device charges the battery in constant current (CC) and constant voltage (CV) states and terminates in a topup-charge state after the taper timer is elapsed. The device resumes charging automatically when the battery voltage falls below the recharge voltage threshold. Detection and preconditioning of deeply discharged batteries are enabled by a deep discharge detection comparator.

The MAX17703 is available in a 24-pin 4mm x 4mm TQFN package with an exposed pad.

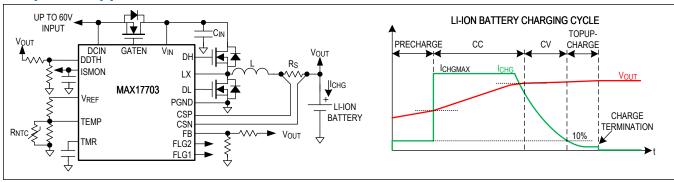
Applications

- Industrial Battery Charging and Energy Storage
- Power Tools and Handheld Terminals
- Battery Backup for Lighting, Security Cameras, and Control Panels
- Portable Industrial and Medical Equipment
- Building and Home-Automation Backup Power

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

Benefits and Features

- Optimized Feature-Set for Li-Ion Batteries Including Li-Polymer, LiFePO₄ and Li-Titanate
 - ±4% Charging Current Regulation Accuracy
 - ±6% Charging Current Monitor Accuracy (ISMON)
 - ±1% Voltage Regulation Accuracy
 - Programmable Constant Current (CC) Mode Charging Current (ILIM)
 - Charge Termination on Full Battery Detection with Taper Current Threshold and Taper Timer
 - Wide 4.5V to 60V Input-Voltage Range
 - Adjustable Output-Voltage Range from 1.25V up to 12 Li-lon cells in series
 - 125kHz to 2.2MHz Adjustable Frequency with External Clock Synchronization (RT/SYNC)
- Reliable Operation in Adverse Environmental Conditions
 - Input Short-Circuit Protection (GATEN)
 - Safety Timer Feature (TMR)
 - Deeply Discharged Battery Detection and Preconditioning (DDTH)
 - Battery Temperature Sensing and Charge when Within Temperature of Range (TEMP)
 - Cycle-by-Cycle Overcurrent Limit
 - Programmable EN/UVLO Threshold
 - Status Output Monitoring Using Open-Drain Outputs (FLG1 and FLG2)
 - Overtemperature Protection
 - Complies with CISPR 32 (EN55032) Class B Conducted and Radiated Emissions
 - Wide -40°C to +125°C Ambient Operating Temperature Range/ -40°C to +150°C Junction Temperature Range



Simplified Application Circuit

<u>Ordering Information</u> appears at end of data sheet.

19-100908; Rev 1; 12/21

© 2022 Analog Devices, Inc. All rights reserved. Trademarks and registered trademarks are the property of their respective owners.

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

Absolute Maximum Ratings

V _{IN} to SGND/EP0.3V to +65V	BST to PGND0.3V to +70V
DCIN to SGND/EP	DL to PGND0.3V to (V _{CC} + 0.3V)
GATEN to DCIN	DH to LX0.3V to (BST + 0.3V)
GATEN to SGND/EP max(-0.3V, DCIN - 0.3V) to (DCIN + 6V)	EXTVCC to SGND/EP0.3V to +26V
V _{CC} to SGND/EP0.3V to min(+6V, V _{IN} + 0.3V)	PGND to SGND/EP0.3V to +0.3V
CSN, CSP to SGND/EP0.3V to (V _{IN} + 0.6V)	Continuous Power Dissipation ($T_A = +70^{\circ}C$) TQFN (derate
CSP to CSN0.3V to +0.3V	27.85mW/°C above +70°C)2222mW
V _{REF} , TMR, ILIM to SGND/EP0.3V to (V _{CC} + 0.3V)	Operating Temperature Range (Note 1)40°C to +125°C
COMP, ISMON, RT/SYNC to SGND/EP0.3V to (V _{CC} + 0.3V)	Junction Temperature+150°C
DDTH, FB, TEMP to SGND/EP0.3V to +6V	Storage Temperature Range65°C to +150°C
FLG1, FLG2, EN/UVLO to SGND/EP0.3V to +6V	Lead Temperature (soldering, 10s)+300°C
LX to PGND0.3V to +65V	Soldering Temperature (reflow)+260°C
BST to LX0.3V to +6V	

Note 1: Junction temperature greater than +125°C degrades operating lifetimes.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Package Information

24 TQFN

Package Code	T2444+5C
Outline Number	<u>21-100405</u>
Land Pattern Number	<u>90-100139</u>
THERMAL RESISTANCE, FOUR-LAYER BOARD	
Junction to Ambient (θ_{JA})	36°C/W
Junction to Case (θ_{JC})	3°C/W

For the latest package outline information and land patterns (footprints), go to <u>www.maximintegrated.com/packages</u>. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to <u>www.maximintegrated.com/</u> <u>thermal-tutorial</u>.

Electrical Characteristics

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS		
POWER SUPPLY								
DCIN Voltage Range		DCIN connected to V _{IN} , External nMOSFET not used	4.5		60	v		
		External nMOSFET used	5.5		60			
V _{IN} Voltage Range			4.5		60	V		
Input Quiescent Current	I _{QNS}	(V _{IN} - V _{CSN}) > 2.1V, V _{FB} = 1.5V	1.4	2.1	2.8	mA		
Input Switching Current	I _{QS}		1.7	2.5	3.5	mA		

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

Electrical Characteristics (continued)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
Shutdown Supply Current	I _{IN-SH}	V _{EN/UVLO} = 0V (shutdown mode)		7	18	μA	
ENABLE/UVLO (EN/UVL	O)					•	
EN/UVLO Rising Threshold	V _{EN_TH_R}	V _{EN/UVLO} rising	1.22	1.25	1.27	V	
EN/UVLO Falling Threshold	V _{EN_TH_F}		1.07	1.09	1.11	V	
EN/UVLO Bias Current	I _{EN-BIAS}	V _{EN/UVLO} = 0.5V	1.4	3.0	6.5	μA	
EN/UVLO True Shutdown Threshold	V _{ENT}	V _{EN/UVLO} rising Hysteresis	0.4	0.7	1.1	V mV	
V _{CC} REGULATORS (INT	LDO AND EXT						
V _{CC} Output Voltage		6V < V _{IN} < 60V, I _{VCC} = 1mA (V _{CC} supplied from INT-LDO)	5.00	5.15	5.30		
		V _{IN} = 24V, I _{VCC} = 0mA to 75mA, (V _{CC} supplied from INT-LDO)	4.95	5.10	5.25		
	V _{CC}	6V < V _{EXTVCC} < 24V, I _{VCC} = 1mA (V _{CC} supplied from EXT-LDO)	5.00	5.15	5.30	V	
		V_{EXTVCC} = 12V, I_{VCC} = 0mA to 75 mA, (V_{CC} supplied from EXT-LDO)	4.95	5.10	5.25		
V _{CC} Output-Current	h	V_{IN} = 8.5V, V_{CC} = 4V (V_{CC} supplied from INT-LDO)	80	110	135	mA	
Limit	IVCC_LIMIT	V_{EXTVCC} = 8.5V, V_{CC} = 4V (V_{CC} supplied from EXT-LDO)	80	110	135	ma	
		V _{IN} = 4.5V, I _{VCC} = 75mA (V _{CC} supplied from IN-LDO)		370	750		
V _{CC} Dropout Voltage	V _{CC-DO}	V _{EXTVCC} = 4.9V, I _{VCC} = 75mA (V _{CC} supplied from EXT-LDO)		185	350	— mV	
V _{CC} Undervoltage	V _{CC-UVR}	V _{CC} rising	4.14	4.20	4.26	- v	
Threshold	V _{CC-UVF}	V _{CC} falling	3.74	3.80	3.86	v	
EXTVCC Voltage Range			4.8		24	V	
EXTVCC Switchover		V _{EXTVCC} rising	4.63	4.70	4.77	v	
Voltage		Hysteresis		0.24			
OSCILLATOR (RT/SYNC)						
		R _{RT/SYNC} = 350 kΩ	118.75	125	131.25		
Switching Frequency	f _{SW}	R _{RT/SYNC} = unconnected	332.5	350.0	367.5	kHz	
	'200	R _{RT/SYNC} = 110kΩ	380	400	420	KПZ	
		R _{RT/SYNC} = 19kΩ	2090	2200	2310		
Synchronization Frequency Range	fsync		0.9 x f _{SW}		1.1 x f _{SW}	kHz	
External Clock Amplitude		C _{COUPLING} = 10pF	3			V	

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

Electrical Characteristics (continued)

PARAMETER	SYMBOL	COND	DITIONS	MIN	TYP	MAX	UNITS	
SYNC High Pulse Width				100			ns	
SYNC Low Pulse Width				100			ns	
SYNC Input-Leakage Current	ISYNC_LKG	V _{RT/SYNC} = 2.5V, T	_A = +25°C	-100		+100	nA	
GATE DRIVER				-				
DH to BST On- Resistance		Source 100mA		0.8	1.2	2.1	Ω	
DH to LX On-Resistance		Sink 100mA		0.3	0.6	1.0	Ω	
DL to V _{CC} On- Resistance		Source 100mA		0.8	1.2	2.1	Ω	
DL to PGND On- Resistance		Sink 100mA		0.3	0.6	1.0	Ω	
DH Minimum Controlled On-Time	^t MIN_ON_DH			60	80	100	ns	
DL Minimum Guaranteed On-Time	^t MIN_ON_DL			60	80	100	ns	
Deed Time	^t DT_HL	DH falling to DL risir C _{DL-PGND} = 6nF	DH falling to DL rising, $C_{DH-LX} = 6nF$, $C_{DL-PGND} = 6nF$		30		ns	
Dead Time	t _{DT_LH}	DL falling to DH rising, $C_{DH-LX} = 6nF$, $C_{DL-PGND} = 6nF$			30	30		
DH Transition Time	t _{HR}	DH rising, C _{DH-LX} = 6nF			25		20	
	t _{HF}	DH falling, C _{DH-LX} = 6nF			11		ns	
DL Transition Time	t _{LR}	DL rising, C _{DL-PGNE}	DL rising, C _{DL-PGND} = 6nF		25		ns	
	t _{LF}	DL falling, C _{DL-PGND} = 6nF			11		115	
REFERENCE VOLTAGE	(V _{REF})			-				
V _{REF} Output Voltage	V _{REF}	I _{VREF} = 0 to 1mA		2.465	2.500	2.535	V	
Reference Current Limit	IREF_LIM	V _{REF} = 2.45V		1.2	1.8	2.7	mA	
CURRENT SENSE (CSP,	CSN, ILIM)			-				
CSP, CSN Common- Mode Voltage Range				0		(V _{IN} - 2)	V	
CSP-to-CSN Input Operating Voltage	V _{DIFF_CS}	$V_{DIFF_CS} = (V_{CSP} -$	V _{CSN})	-10		+100	mV	
		V _{ILIM} = 1.5V		48	50	52		
CSP-to-CSN Regulation Voltage Accuracy	V _{CSREG}	V _{ILIM} = 0.9V		28	28 30 3	32	mV	
t enage / local acy		V _{ILIM} = V _{REF}		48	50	52		
CSP Pin Current		CSP source			200	1400	nA	
		V _{EN/UVLO} = 0V, CS	N sink		1.3	2.3		
CSN Pin Current	t Charger on. VIIIM	Charger on, V _{ILIM}	I _{CHG} > I _{TCHG} , CSN source	250	400	550	μA	
		= 0.9V to 1.5V	I _{CHG} < I _{TCHG} , CSN sink	470	700	1000		

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

Electrical Characteristics (continued)

PARAMETER	SYMBOL	CONE	DITIONS	MIN	TYP	MAX	UNITS
Current-Loop-Error Amplifier Transconductance	9mi	$(V_{CSP} - V_{CSN}) = V_{CSREG} \pm 25mV$		275	480	685	μS
ILIM Input Leakage Current		V _{ILIM} = 1.5V, T _A = 2	-100		100	nA	
CSN Undervoltage		(V _{IN} - V _{CSN}), rising		1.97	2.04	2.10	- v
Lockout Threshold	VCMUVLO	(V _{IN} - V _{CSN}), falling		1.88	1.95	2.02	v
Overcurrent Threshold	V _{CS_PEAK}	V _{CS_PEAK} = (V _{CSP} 1.5V	- V _{CSN}), V _{ILIM} =	70	75	80	mV
		Hysteresis			10		
Zero-Cross Threshold	V _{ZX}	(V _{CSP} - V _{CSN}) fallin	g	3	4.5	6	mV
PWM-Ramp Amplitude	V _{RAMP}	f _{SW} = 125kHz to 2.2	MHz	1.37	1.44	1.51	V
VOLTAGE REGULATION	I AMPLIFIER (F	В)					
FB Reference Voltage	V _{FB_REG}			1.237	1.250	1.263	V
FB Input-Leakage Current		V _{FB} = 1.3V, T _A = +2	25°C	-100		100	nA
Voltage-Loop-Error Amplifier Gain	G _V			1.15	1.30	1.42	mV/mV
FB to SGND/EP Short Fault Threshold	V _{FBGND}	V _{FB} < V _{FBGND}		57	65	73	mV
INPUT SHORT-CIRCUIT	PROTECTION (GATEN)					
External nMOSFET Gate Drive Voltage	(V _{GATEN} - V _{DCIN})			4.65	5	5.50	V
GATEN Drive Current	IGATEN			17	20	23	μA
GATEN Active Pulldown Resistance	R _{GATEN_} A	I _{GATEN} = 100mA			1.1	2.1	Ω
GATEN Passive Pulldown Resistance	R _{GATEN_P}	V _{EN/UVLO} = 0V			400	800	Ω
GATEN-DCIN Threshold	V _{GATEN_} OK			3.20	3.55	3.90	V
GATEN OK Delay	tGATEN_OK				15		ms
External nMOSFET		(V _{DCIN} - V _{IN}) falling		-111	-93	-75	
Reverse-Blocking Threshold	V _{REV}	Hysteresis			20		mV
External nMOSFET Reverse-Blocking Response Time		C _{GATEN-DCIN} = 10nF, V _{DCIN} < (V _{IN} - 93mV) to (V _{GATEN} - V _{DCIN}) < 2V			100	180	ns
V _{IN} to DCIN Reverse Leakage Current		V _{DCIN} = 0V, V _{IN} = 60V	V _{EN/UVLO} = 0V		170 230	260 350	- μΑ
CHARGER FUNCTIONS		I	1				1
Constant-Voltage (CV)		V _{ILIM} = 1.5V, V _{FB} ri	sing	97.15	97.50	97.85	% of
lode FB Threshold V _{FB_CV} Hysteresis			0.3		V _{FB_REG}		

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

Electrical Characteristics (continued)

SYMBOL	COND	MIN	TYP	MAX	UNITS	
M	V _{FB} falling		94.5	95	95.5	% of
^V RECHG	Hysteresis			0.56		V _{FB_REG}
	V _{DDTH} rising		1.245	1.260	1.275	
V _{DDREF}	V _{DDTH} falling	V _{DDTH} falling		1.250	1.265	V
		V _{ILIM} = 1.5V	2.5	5	7.5	
VCSPCHG	$V_{\text{DDTH}} = 1.1V$	V _{ILIM} = 0.9V	0.5	3	5.5	mV
I _{TCHG}	Current falling (see N	Note 3)	4.8	10	16.8	% of I _{CHGMAX}
	$(V_{CSP} - V_{CSN}) = 50 mV$		1.41	1.50	1.59	- v
	(V _{CSP} - V _{CSN}) = 30r	mV	0.825	0.900	0.975	v
				90		kΩ
				100		kHz
						•
1	C _{TMR} = 220nF	C _{TMR} = 220nF		55		
^I CH_START	TMR disabled			54		- ms
V _{TMR_H}			1.47	1.50	1.53	V
V _{TMR_L}			0.94	0.96	0.98	V
I _{TMR}			8.9	10	10.9	μA
V _{TMR_DIS}	V _{TMR} > V _{TMR_DIS} (power-up check only)	1.9	2.0	2.1	V
V _{TMR_GND}	V _{TMR} < V _{TMR_GND} only)	(power-up check	80	100	120	mV
t _{FCHG}				1048575		TMR CYCLES
t _{PCHG}				131071		TMR CYCLES
t _{TOP}				104857		TMR CYCLES
RE SENSE (TEN	IP)					
\/	Battery temperature	falling	59.4	60	60.6	% of
YTEMPU	Hysteresis			1		V _{REF}
\/	Battery temperature	rising	39.4	40	40.6	% of
VTEMPL	Hysteresis		1.2		V _{REF}	
	VRECHG VDDREF VCSPCHG ITCHG ITCHG ITCHG VTMR_H VTMR_H VTMR_L ITMR VTMR_DIS VTMR_OND tFCHG tPCHG tTOP RE SENSE (TEM VTEMPU	V_{RECHG} V_{FB} falling Hysteresis V_{DDREF} V_{DDTH} rising V_{DDTH} falling V_{CSPCHG} $V_{DDTH} = 1.1V$ I_{TCHG} Current falling (see N (V_{CSP} - V_{CSN}) = 50r (V_{CSP} - V_{CSN}) = 30r I_{TCHG} $(V_{CSP} - V_{CSN}) = 30r$ I_{CH_START} $C_{TMR} = 220nF$ TMR disabled V_{TMR_H} V_{TMR_H} V_{TMR_L} I_{TMR} V_{TMR_R} V_{TMR_SON} V_{TMR_SON} $V_{TMR} < V_{TMR_SON}$ V_{TMR_SON} $V_{TMR} < V_{TMR_SON}$ V_{TCHG} $V_{TMR} < V_{TMR_SON}$ V_{TEMPU} Battery temperature Hysteresis W_{TEMPU} Battery temperature Hysteresis	$\begin{tabular}{ c c c } & V_{FB} falling & & & & & & & & & & & & & & & & & & &$	$\begin{array}{c c c c c c c c c c c c c c c c c c c $	$\begin{array}{c c c c c c c c } & V_{FB} \mbox{ falling } & 94.5 & 95 \\ \hline Hysteresis & 0.56 \\ \hline V_{DDREF} & V_{DDTH} \mbox{ rising } & 1.245 & 1.260 \\ \hline V_{DDTH} \mbox{ falling } & 1.235 & 1.250 \\ \hline V_{CSPCHG} & V_{DDTH} \mbox{ falling (see Note 3)} & 1.235 & 1.250 \\ \hline V_{LIM} \mbox{ falling (see Note 3)} & 0.5 & 3 \\ \hline I_{TCHG} & Current \mbox{ falling (see Note 3)} & 4.8 & 10 \\ \hline & (V_{CSP} \mbox{ - }V_{CSN}) \mbox{ falling (see Note 3)} & 4.8 & 10 \\ \hline & (V_{CSP} \mbox{ - }V_{CSN}) \mbox{ falling (see Note 3)} & 4.8 & 10 \\ \hline & (V_{CSP} \mbox{ - }V_{CSN}) \mbox{ falling (see Note 3)} & 4.8 & 10 \\ \hline & (V_{CSP} \mbox{ - }V_{CSN}) \mbox{ falling (see Note 3)} & 4.8 & 10 \\ \hline & (V_{CSP} \mbox{ - }V_{CSN}) \mbox{ falling (see Note 3)} & 4.8 & 10 \\ \hline & (V_{CSP} \mbox{ - }V_{CSN}) \mbox{ falling (see Note 3)} & 4.8 & 10 \\ \hline & (V_{CSP} \mbox{ - }V_{CSN}) \mbox{ falling (see Note 3)} & 4.8 & 10 \\ \hline & (V_{CSP} \mbox{ - }V_{CSN}) \mbox{ falling (see Note 3)} & 4.8 & 10 \\ \hline & (V_{CSP} \mbox{ - }V_{CSN}) \mbox{ falling (see Note 3)} & 4.8 & 10 \\ \hline & (V_{CSP} \mbox{ - }V_{CSN}) \mbox{ falling (see Note 3)} & 4.8 & 10 \\ \hline & (V_{CSP} \mbox{ - }V_{CSN}) \mbox{ falling (see Note 3)} & 0.825 & 0.900 \\ \hline & (V_{TMR} \mbox{ falling (see Note 3)} & 0.825 & 0.900 \\ \hline & (V_{TMR} \mbox{ falling (see Note 3)} & 0.825 & 0.900 \\ \hline & (V_{TMR} \mbox{ falling (see Note 3)} & 0.825 & 0.900 \\ \hline & (V_{TMR} \mbox{ falling (see Note 3)} & 0.94 & 0.96 \\ \hline & (I_{TMR} \mbox{ falling (see Note 3)} & 0.94 & 0.96 \\ \hline & (I_{TMR} \mbox{ falling (see Note 3)} & 0.94 & 0.96 \\ \hline & (I_{TMR} \mbox{ falling (see Note 3)} & 0.94 & 0.96 \\ \hline & (I_{TMR} \mbox{ falling (see Note 3)} & 0.94 & 0.96 \\ \hline & (I_{TMR} \mbox{ falling (see Note 3)} & 0.94 & 0.96 \\ \hline & (I_{TMR} \mbox{ falling (see Note 3)} & 0.94 & 0.96 \\ \hline & (I_{TMR} \mbox{ falling (see Note 3)} & 0.94 & 0.96 \\ \hline & (I_{TMR} \mbox{ falling (see Note 3)} & 0.94 & 0.96 \\ \hline & (I_{TMR} \mbox{ falling (see Note 3)} & 0.94 & 0.96 \\ \hline & (I_{TMR} \mbox{ falling (see Note 3)} & 0.95 \\ \hline & (I_{TMR} \mbox{ falling (see Note 3)} & $	VRECHG VFB failing Hysteresis 94.5 95 95.5 VDREF VDDTH rising 1.245 1.260 1.275 VDDREF VDDTH failing 1.235 1.260 1.275 VCSPCHG VDDTH failing 1.235 1.260 1.275 VCSPCHG VDDTH = 1.1V VILIM = 1.5V 2.5 5 7.5 ITCHG Current failing (see Note 3) 4.8 10 16.8 (VCSP - VCSN) = 50mV 1.41 1.50 1.59 (VCSP - VCSN) = 30mV 0.825 0.900 0.975 90 100 100 100 tCH_START CTMR = 220NF 55 55 TMR disabled 54 100 100 VTMR_LL 0.94 0.96 0.98 ITMR 8.9 10 10.9 VTMR_LL 0.94 0.96 0.98 ITMR 8.9 10 10.9 VTMR_GND VTMR_OIS (power-up check only) 1.9 2.0 2.1

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

Electrical Characteristics (continued)

 $(V_{IN} = V_{DCIN} = 24V, C_{VIN} = 4.7\mu$ F, $C_{DCIN} = 100$ nF, $C_{VCC} = 4.7\mu$ F, $C_{VREF} = 100$ nF, $C_{BST} = 470$ nF, $(V_{BST} \text{ to } V_{LX}) = 5V$, $V_{EN/UVLO} = V_{LX} = V_{ILIM} = V_{CSN} = V_{CSP} = V_{DDTH} = V_{TMR} = 2.5V$, $V_{TEMP} = V_{FB} = 1.1V$, $V_{EXTVCC} = V_{SGND/EP} = V_{PGND} = 0V$, RT/SYNC = DH = DL = GATEN = COMP = FLG1 = FLG2 = ISMON = Unconnected, $T_A = -40^{\circ}$ C to $+125^{\circ}$ C, unless otherwise noted. Typical values are at the composition of the comp T_A= +25°C. All voltages are referenced to SGND/EP, unless otherwise noted.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS		
CHARGER STATUS OUT	CHARGER STATUS OUTPUTS (FLG1, FLG2)							
FLG1/FLG2 Pulldown Voltage		I _{FLG1} , I _{FLG2} = 10mA			500	mV		
FLG1/FLG2 Leakage Current		V _{FLG1} , V _{FLG2} = 5.5V, T _A = +25°C	-100		+100	nA		
IC THERMAL PROTECT	ON	·						
Thermal Shutdown Threshold		Temperature rising		160		°C		
Thermal Shutdown Hysteresis				10		°C		

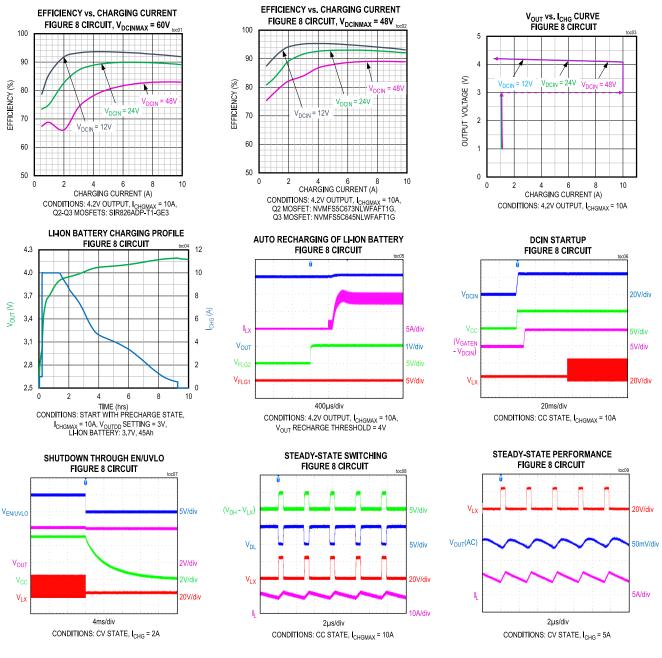
Note 2: Electrical specifications are production tested at T_A = +25°C. Specifications over the entire operating temperature range are guaranteed by design and characterization.

Note 3: CC mode charging current setting is calculated using the following equation $I_{\text{CHGMAX}} = \frac{V_{\text{CSREG}}}{R_{S}}$, where R_S is the current-sense resistor.

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

Typical Operating Characteristics

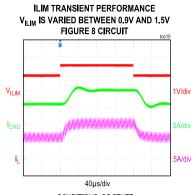
 $(V_{DCIN} = 24V, V_{SGND/EP} = V_{PGND} = 0V, RT/SYNC = unconnected (f_{SW} = 350kHz), T_A = +25^{\circ}C$, unless otherwise noted. All voltages are referenced to SGND/EP, unless otherwise noted.)

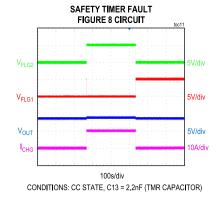


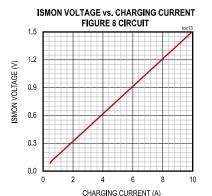
4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

Typical Operating Characteristics (continued)

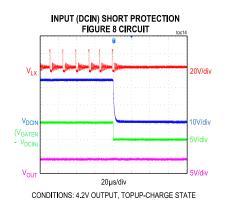
 $(V_{DCIN} = 24V, V_{SGND/EP} = V_{PGND} = 0V, RT/SYNC = unconnected (f_{SW} = 350kHz), T_A = +25^{\circ}C$, unless otherwise noted. All voltages are referenced to SGND/EP, unless otherwise noted.)



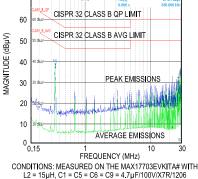


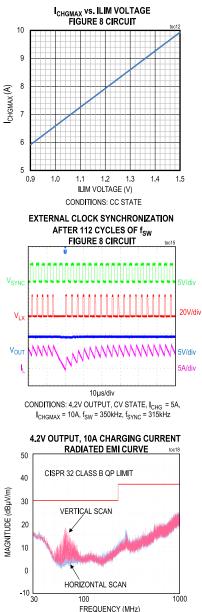


TEMP CHARGING DISABLE AND ENABLE **FIGURE 8 CIRCUIT** V_{FLG1} 5V/div V_{FLG2} 5V/div 44°C 42°C VTEM 0.5V/div V_{LX} 20V/div 20s/div CONDITIONS: CC STATE









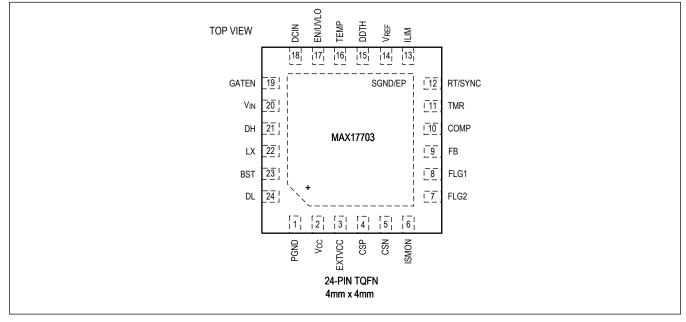
CONDITIONS: MEASURED ON THE MAX17703EVKITA#

CONDITIONS: CC STATE

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

Pin Configuration

MAX17703



Pin Description

PIN	NAME	FUNCTION
1	PGND	Power Ground. Connect to the return terminal of a V_{CC} bypass capacitor placed close to the IC and the source terminal of external low-side nMOSFET. Refer to the MAX17703 evaluation kit data sheet for the PCB layout example.
2	V _{CC}	Internal LDO Output. Connect a minimum of 4.7 μ F/0805, low-ESR ceramic capacitor between V _{CC} and PGND. V _{CC} supports IC internal-control circuitry and gate-drive current for external nMOSFETs.
3	EXTVCC	External Power-Supply Input for EXT-LDO. To power internal circuitry from an external supply, apply a voltage between 4.8V and 24V to the EXTVCC pin. Connect a minimum of 1µF/0603, low-ESR ceramic capacitor between EXTVCC and SGND/EP. Leave EXTVCC open when not used.
4	CSP	Inverting Input of the Current Loop Error Amplifier. The CSP and CSN pins measure the voltage across the current sense resistor R_S (see Figure 5).
5	CSN	Non-Inverting Input of the Current-Loop-Error Amplifier. Connect CSN to the node connecting the output capacitor and current sense resistor R_S . Use Kelvin connections and route the CSP and CSN traces as a differential pair (see Figure 5).
6	ISMON	Output of Charging Current Monitor. Bypass ISMON with a 1nF low-ESR ceramic capacitor to SGND/EP. The voltage on this pin is 30 times the voltage drop across the current-sense resistor (R_S).
7, 8	FLG2, FLG1	Open Drain Status Output Pins. Connect one $10k\Omega$ pullup resistor each from V _{CC} to FLG1 and FLG2. See the <u>Charger Status Outputs (FLG1, FLG2)</u> section for more details.
9	FB	Feedback Input. Connect FB to the center node of a resistor-divider from the positive terminal of the battery to SGND/EP to set the output voltage. See the <u>Setting Output Voltage and Voltage</u> <u>Regulation Loop (FB)</u> section for more details.
10	COMP	Current Loop Error Amplifier Output. Connect a compensation network at this pin to stabilize the inner current loop. See the <u>Current Regulation Loop Compensation (COMP)</u> section for more details.

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

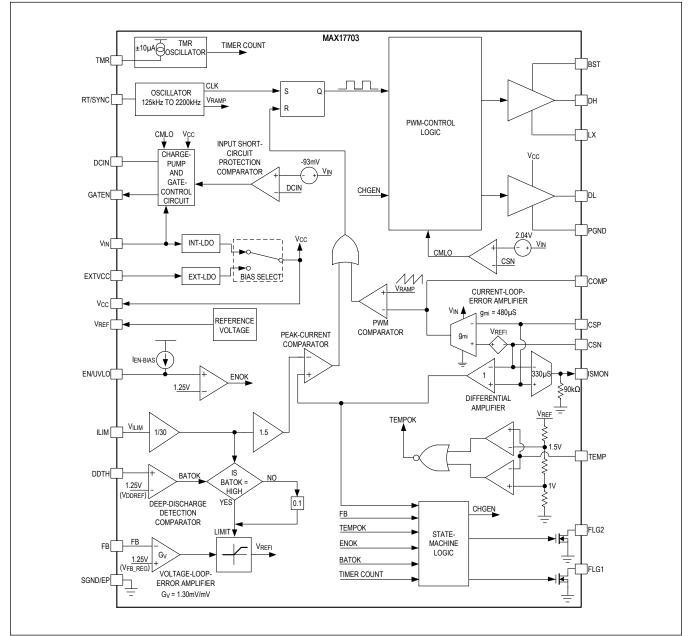
Pin Description (continued)

NAME	FUNCTION
TMR	Battery Safety Timer Setting Pin. A capacitor from TMR to SGND/EP sets the charging time in precharge, CC, CV, topup-charge states. Place the timer capacitor close to the TMR pin. Connect TMR to V _{REF} to disable the timer function. See the <u>Charger Timers (TMR)</u> section for more details.
RT/SYNC	Switching Frequency Programming/Synchronization Input. Connect a resistor from RT/SYNC to SGND/EP to set the switching frequency between 125kHz to 2.2MHz. Leave RT/SYNC open for the default 350kHz frequency. See the <u>Setting the Switching Frequency and External Clock</u> <u>Synchronization (RT/SYNC)</u> section for more details.
ILIM	CC Mode Charging Current Programming Input. Connect ILIM to the center node of a resistor divider between V _{REF} and SGND/EP to set the CC mode charging current. Connect to V _{REF} for the default CC mode charging current. See the <u>CC Mode Charging Current Setting (ILIM)</u> section for more details.
V _{REF}	2.5V Reference Output. Bypass V_{REF} with a 0.1µF low-ESR ceramic capacitor to SGND/EP. See the <u>Reference Voltage (V_{REF}</u>) section for more details.
DDTH	Battery Deep-Discharge Detection Input. Connect DDTH to the center node of a resistor divider from the output-voltage node to SGND/EP. If V _{DDTH} falls below V _{DDREF} , the charger enters the precharge state for battery preconditioning. See the <u>Setting the Deep Discharge Voltage Level</u> (<u>DDTH</u>) and <u>Power-Up/Down Sequence and Charger Operation</u> sections for more details.
TEMP	Battery Temperature Input. Connect TEMP to the center node of a resistor divider from V _{REF} to SGND/EP. Connect the battery temperature sensing NTC resistor terminals across the bottom resistor of the divider to program the battery charging temperature window. See the <u>Setting Battery</u> <u>Operating Temperature Range (TEMP)</u> section for more details.
EN/UVLO	Enable/Undervoltage-Lockout Input. Connect to the center node of a resistor divider between DCIN and SGND/EP to set the input voltage at which the device turns on. Connect to SGND/EP to shutdown the device. See the <u>Setting the Input Undervoltage-Lockout Level (EN/UVLO)</u> section for more details.
DCIN	Input-Supply-Voltage Sense Pin. Bypass DCIN with a 0.1 μ F ceramic capacitor to PGND. The DCIN and V _{IN} pins measure the voltage across external nMOSFET. Use Kelvin connections and route the V _{IN} and DCIN traces as differential pair. Refer to the MAX17703 EV kit data sheet for the recommended PCB layout and routing. If input short-circuit protection feature is not used, connect DCIN to V _{IN} close to IC.
GATEN	Gate Drive Output for External nMOSFET. Bypass GATEN with a 2.2nF low-ESR ceramic capacitor to DCIN. GATEN controls the gate of an external nMOSFET connected between DCIN and V_{IN} to prevent battery discharge when DCIN is shorted to PGND. See the <u>Input Short Circuit</u> <u>Protection (GATEN)</u> section for more details.
V _{IN}	MAX17703 IC-Supply Pin. Bypass V _{IN} to PGND with a 0.1 μ F ceramic capacitor. Refer to the MAX17703 EV kit data sheet for the recommended PCB layout and routing.
DH	High-Side nMOSFET Gate Driver Output. Connect to the gate of the high-side nMOSFET.
LX	Switching Node Connection Input. Connect to the switching node of the converter.
BST	Bootstrap Capacitor Connection Input. Connect a capacitor of 0.1μ F (min) between the BST and LX pins. Connect a Schottky diode from the V _{CC} to the BST pin. See the <u>Bootstrap Capacitor</u> <u>Selection</u> and <u>Bootstrap Diode Selection</u> sections for more details.
DL	Low-Side nMOSFET Gate Driver Output. Connect to the gate of the low-side nMOSFET.
SGND/EP	Signal Ground, Exposed Pad. Refer to the MAX17703 EV kit data sheet for the recommended method of PCB layout, routing, and thermal vias.
	TMR RT/SYNC ILIM VREF DDTH TEMP EN/UVLO DCIN GATEN UN DH LX BST DL

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

Functional Diagrams

MAX17703



4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

Detailed Description

The MAX17703 is a 4.5V to 60V wide input, synchronous, step-down Li-ion battery-charger controller designed to operate over a -40°C to +125°C temperature range. It offers a complete battery charge cycle solution for Li-ion batteries including Li-Polymer, LiFePO₄, and Li-Titanate. Charging begins in one of the three states, namely, precharge, constant current (CC), and constant voltage (CV) depending on the battery voltage. The charger enters a topup-charge state when the charging current reduces to the taper-current threshold. Charging is terminated in the topup-charge state, when the taper-timer period elapses. The MAX17703 initiates a recharge cycle when output voltage falls below the recharge threshold voltage. The device provides input short-circuit protection, and prevents battery discharging for input supply-side short-circuit events by means of an external nMOSFET. The MAX17703 offers up to $\pm4\%$ accurate constant charging current in CC mode and regulates the no-load output voltage with $\pm1\%$ accuracy. The MAX17703 supports a wide adjustable output-voltage range of 1.25V to (V_{DCIN} - 2.1V).

The MAX17703 features a constant frequency, average current-mode control architecture shown in Figure 1. An internal current loop consists of a transconductance amplifier (g_{mi}) that senses the inductor current flowing through current-sense resistor (R_S) as a voltage drop across the CSP and CSN pins. The current-sense voltage is compared with a current-loop reference voltage (V_{REFI}), which is set by the outer-voltage loop-error amplifier (G_V) and limited by the voltage programmed at the ILIM pin (V_{ILIM}). The voltage at the COMP pin is compared with a 1.44V (typ) ramp using a PWM comparator to set the duty cycle of the converter. The required compensation to stabilize the current loop is applied at the COMP pin using R_Z , C_Z , and C_P . Under steady-state conditions, the inner current loop forces the voltage drop across R_S equal to V_{REFI} .

The output voltage is monitored by the voltage error amplifier G_V with a resistor divider (R_{TOP} and R_{BOT}) connected across the positive and negative battery terminals with the center node connected to the FB pin. The voltage at the FB pin is compared with the FB reference voltage (V_{FB} REG). The voltage-loop-error amplifier sets the current-loop

reference voltage (V_{REFI}). V_{REFI} is limited to $\frac{V_{\text{ILIM}}}{30}$ until $V_{\text{FB}} \leq \left[V_{\text{FB}_{\text{REG}}} - \frac{V_{\text{ILIM}}}{30 \times G_V}\right]$. This results in constant current

through R_S. When the output voltage rises such that, $V_{FB} > \left[V_{FB_REG} - \frac{V_{ILIM}}{30 \times G_V}\right]$, V_{REFI} ; hence, the charging current (I_{CHG}) proportionately reduces. The charging current for a given output voltage (V_{OUT_SS}) is given by the following equation:

$$I_{\text{CHG}} = \left(V_{\text{FB}_{\text{REG}}} - V_{\text{OUT}_{\text{SS}}} \times \left(\frac{R_{\text{BOT}}}{R_{\text{TOP}} + R_{\text{BOT}}} \right) \right) \times \frac{G_V}{R_S}$$

where,

V_{FB REG} = FB reference voltage

V_{OUT_SS} = Output voltage

I_{CHG} = Charging current of the charger for a given output voltage

R_{TOP} and R_{BOT} = Output voltage feedback divider resistors

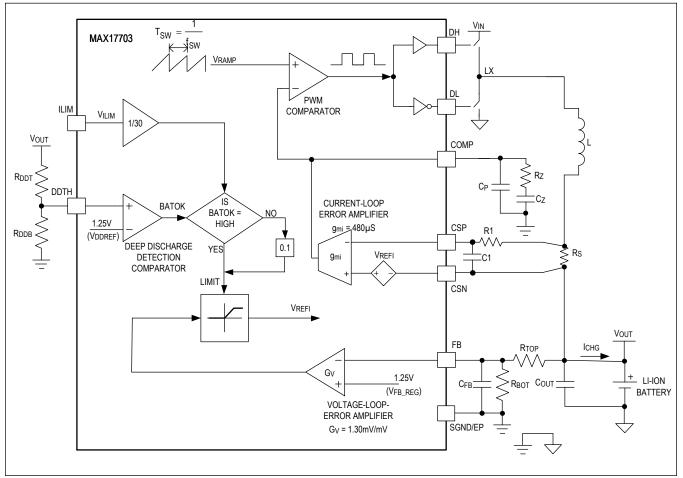
 G_V = Voltage loop error amplifier gain (1.30mV/mV)

Deeply discharged batteries can be detected by using the deep-discharge detection comparator with a resistor divider (R_{DDT} and R_{DDB}) connected across the positive and negative battery terminals with the center node connected to the DDTH pin. When $V_{DDTH} < 1.25V$ (V_{DDREF}), the battery is considered to be deeply discharged and the charger enters a

precharge state to revive the deeply discharged battery. In precharge state, V_{REFI} is limited to $\frac{V_{ILIM}}{300}$ to limit the charging current to 10% of the CC mode charging current. A safety timer (TMR) sets the maximum allowed charging time in precharge, CC, and CV states to improve system safety.

A NTC sense resistor can be used with MAX17703 to sense battery temperature (TEMP) and charge only within the allowed battery temperature range. The switching frequency of the device can be programmed from 125kHz to 2.2MHz using a resistor at the RT/SYNC pin. RT/SYNC also provides an external clock synchronization feature. Input undervoltage lockout is implemented using the EN/UVLO pin. Two open-drain status outputs (FLG1 and FLG2) indicate

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller



the battery charger status. And, the charging current can be monitored using the ISMON pin.

Figure 1. Average Current-Mode Control Loop

Power-Up/Down Sequence and Charger Operation

<u>Figure 2</u> shows both the MAX17703 power-up/down sequence when the DCIN voltage is applied/removed, and a Li-ion battery charge cycle. <u>Figure 3</u> shows the Charger-State diagram of the IC. MAX17703 offers precharge, constant-current (CC), constant-voltage (CV), and topup-charge states for charging Li-ion batteries.

When the DCIN voltage reaches a level such that $V_{EN/UVLO}$ is around 0.7V (V_{ENT}), the INT-LDO regulator is enabled and V_{CC} rises. When V_{CC} rises above 4.2V (V_{CC-UVR}) and $V_{EN/UVLO}$ rises above 1.25V ($V_{EN_TH_R}$), the MAX17703 enters a powerup-check state from the charger-off state, initiates EN/UVLO debounce, and checks for hardware faults. If there are no hardware faults detected at power-up (see the <u>Charger Status Outputs (FLG1, FLG2)</u> section), the MAX17703 enables internal blocks during the charger startup delay time (t_{CH_START}).

After the t_{CH_START} delay, the charger enters a full-battery state from the powerup-check state if V_{FB} > 1.19V (V_{RECHG}). The charger initiates LX switching, enters a precharge state from the powerup-check state if V_{DDTH} < 1.25V (V_{DDREF}). The charger enters CC state from the powerup check state if V_{DDTH} \geq 1.25V (V_{DDREF}).

In the precharge state, the charging current reference ($V_{CSPCHG/RS}$) is set to 10% of the CC mode charging current (I_{CHGMAX}) to precondition the battery and revive it from deep discharge. The safety timer counts the charging time in the precharge state and if the output voltage rises above the deep discharge threshold ($V_{DDTH} > 1.26V$ (V_{DDREF})) within

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

the precharge-timer timeout (t_{PCHG}), the charger exits the precharge state, resets the safety timer counter, and enters CC state. If the safety timer expires in the precharge state ($t_{TC} > t_{PCHG}$), the charger enters a latched-fault state.

If the timer function is disabled, the charger continues to charge in the precharge state until the output voltage rises above deep discharge rising threshold ($V_{DDTH} > 1.26V (V_{DDREF})$) beyond which the charger enters a CC state.

In the CC state, the safety timer counts the charging time, and the charging current (I_{CHG}) is regulated at the CC mode charging current (I_{CHGMAX}) proportional to V_{ILIM} until the output voltage reaches the CV mode threshold ($V_{FB} > 1.219V$ (V_{FB_CV})). When $V_{FB} > 1.219V$ (V_{FB_CV}), the charger exits the CC state and enters a CV state without resetting the safety timer counter. If the safety timer expires in the CC state ($t_{TC} > t_{FCHG}$), the charger enters a latched-fault state.

If the timer function is disabled, the charger continues to charge the battery in the CC state until the output voltage reaches the CV mode threshold ($V_{FB} > 1.219V (V_{FB} CV)$) beyond which the charge enters the CV state.

In the CV state, the charging current is a function of the output voltage. The safety timer continues to count charging time in the CV state. If the charging current (I_{CHG}) tapers naturally down to the taper current threshold (I_{TCHG}) within the safety timer timeout ($t_{TC} < t_{FCHG}$), the timer resets, and the charger exits the CV state and enters a topup-charge state. If the safety timer expires in the CV state ($t_{TC} > t_{FCHG}$), the charger enters the latched-fault state.

If the timer function is disabled, the charger continues to charge the battery in CV state until the $I_{CHG} < I_{TCHG}$ is detected. The charger skips the topup-charge state and enters a full-battery state upon detecting $I_{CHG} < I_{TCHG}$ in a CV state.

In the topup-charge state, the charging current is again a function of the output voltage. The safety timer starts counting the charging time in the topup-charge state. The charger exits the topup-charge state and enters a full-battery state when the safety timer in the topup-charge state ($t_{TC} > t_{TOP}$) elapses.

In the full-battery state, the timer stops counting and resets, and the charging is suspended until the $V_{FB} < 1.19V$ (V_{RECHG}). When $V_{FB} < 1.19V$ (V_{RECHG}), the charger exits the full-battery state, enters CC state, and restarts charging.

In any of the charging states (precharge, CC, CV and topup-charge), if battery operating temperature is detected out of the set range (TEMP Fault condition), the charger enters the respective suspend state (precharge suspend, CC suspend, CV suspend, and topup suspend) and pauses the timer. Upon entering back to an allowed operating temperature range (Exit TEMP Fault condition), the timer resumes, and charging resumes back to the previous state. If the timer function is disabled, the charger enters or exits the charge suspend state based on the battery operating temperature range.

When $V_{EN/UVLO}$ falls below 1.09V ($V_{EN_TH_F}$), the MAX17703 initiates a shutdown sequence with a debounce time of 2ms (typ). If the input voltage decreases such that ($V_{IN} - V_{CSN}$) falls below the current-loop-error amplifier undervoltage-lockout falling threshold (V_{CMUVLO} = 1.95V), the MAX17703 initiates a shutdown sequence immediately. The converter stops switching, and GATEN is pulled down with 1.1 Ω (R_{GATEN_A}) to DCIN to turn off the external nMOSFET. The COMP is pulled low after a debounce time of 100µs (typ).

If $V_{EN/UVLO}$ falls below 0.64V (V_{ENT}), the MAX17703 initiates a shutdown sequence with a debounce time of 10µs (typ). During this shutdown sequence, the MAX17703 pulls down the GATEN with 1.1 Ω (R_{GATEN_A}) to DCIN to turn off the external nMOSFET. See the <u>Setting the Input Undervoltage-Lockout Level (EN/UVLO</u>) section for more details.

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

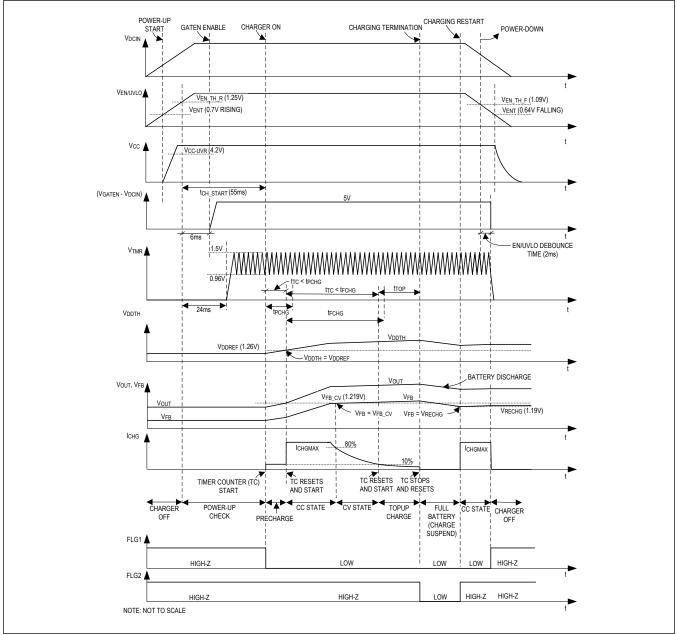


Figure 2. Charger Power-Up/-Down Sequence and Li-Ion Battery Charge Cycle

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

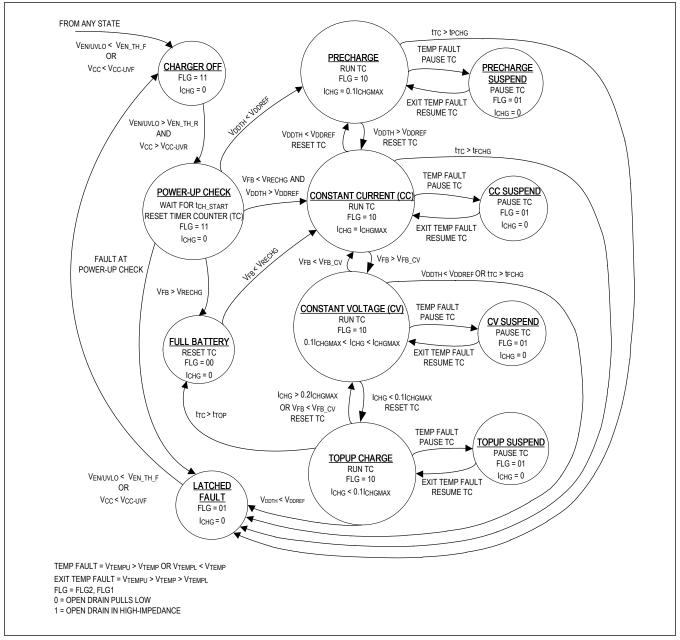


Figure 3. Charger-State Diagram

Input Short-Circuit Protection (GATEN)

The MAX17703 provides a gate drive output (GATEN) that drives a logic-level gate-threshold external nMOSFET, which turns off and prevents battery discharging for input supply short-circuit events. The GATEN is pulled up with 20µA (I_{GATEN}) when V_{IN} is 2.04V (V_{CMUVLO}) above V_{CSN} . If V_{GATEN} does not reach 3.55V (V_{GATEN_OK}) within 15ms (t_{GATEN_OK}), MAX17703 enters a latched-fault state.

Figure 4 depicts the MAX17703 behavior when DCIN is shorted to PGND. When V_{DCIN} is 93mV (V_{REV}) below V_{IN},

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

GATEN is pulled down with 1.1 Ω (R_{GATEN_A}) and the external nMOSFET is turned off within 100ns (typ). When V_{EN/} UVLO goes below 0.64V (V_{ENT}), the MAX17703 shuts down with 10µs (typ) debounce time. When DCIN-to-PGND short is removed, a power-up sequence is initiated (see the *Power-Up/Down Sequence and Charger Operation* section).

Measure the differential voltage between the source and drain terminals of the input short-circuit protection external nMOSFET using a Kelvin connection. Shield DCIN, V_{IN} and GATEN signal traces using static ground plane on either side of the traces and on the adjacent layers of PCB. Place the 0.1μ F decoupling capacitors on DCIN and VIN pins close to MAX17703. The MAX17703 EV kit depicts the recommended layout and routing of DCIN, V_{IN} and GATEN traces.

When the input short-circuit protection is not used, connect a 2.2nF capacitor between GATEN and DCIN, and short DCIN to V_{IN} .

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

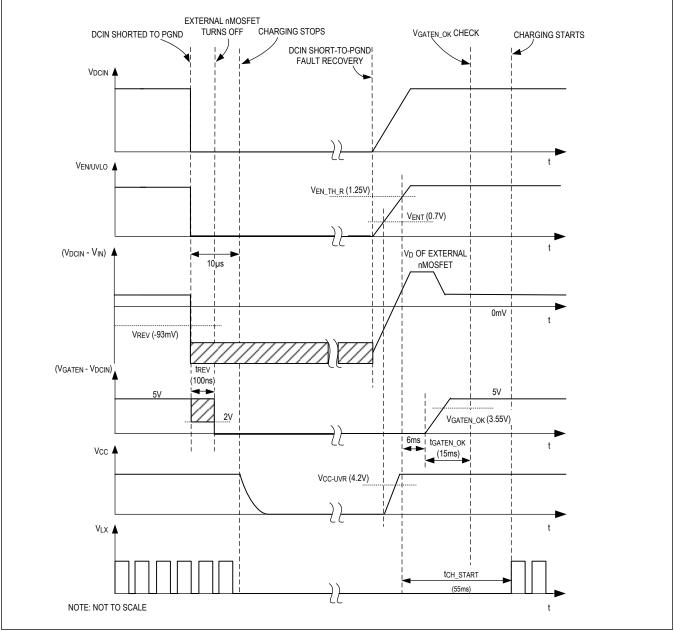


Figure 4. Input Short-Circuit Protection and Recovery Timing Diagram

Charger Timers (TMR)

The MAX17703 offers a programmable timer feature to provide battery charge-cycle control. Connect a capacitor from TMR to SGND/EP to use the timer feature. Connect TMR to V_{REF} to disable the timer feature. The timer counts the charging time in precharge, CC, CV, and topup-charge states.

In the precharge state, if V_{DDTH} does not reach 1.26V (V_{DDREF}) within the precharge timer count (t_{PCHG}), the charger enters a latched-fault state.

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

In the CC and CV states, if the safety timer count (t_{FCHG}) elapses, the charger enters a latched-fault state.

In the topup-charge state, the charger terminates charging and enters a full-battery state, when the taper-timer count (t_{TOP}) elapses.

Table 1 shows the relative timer counts in different states.

Table 1. Charger Timers

STATE	TIMER COUNT
Precharge	t _{PCHG} = t _{FCHG} /8
CC, CV	tғснg
Topup Charge	t _{TOP} = t _{FCHG} /10

The MAX17703 supports 2.2nF to 10μ F capacitance on the TMR pin, translating to a safety timer timeout period range of 3.6 minutes to 273 hours.

Use the following equation to calculate the C_{TMR} for the required safety timer period in CC and CV states (T_{FCHG}):

$$C_{\text{TMR}} \ge 1.15 \times \left(\frac{T_{\text{FCHG}}}{2 \times t_{\text{FCHG}}}\right) \times \left(\frac{I_{\text{TMR}}}{V_{\text{TMR}_{\text{H}}} - V_{\text{TMR}_{\text{L}}}}\right)$$

where,

T_{FCHG} = Desired safety timer setting in CC and CV states in seconds

C_{TMR} = TMR capacitor in Farad

t_{FCHG} = Number of TMR cycles in CC and CV states (1048575)

 V_{TMR} H = TMR oscillator upper threshold (1.5V)

 $V_{TMR L}$ = TMR oscillator lower threshold (0.96V)

I_{TMR} = TMR pin source/sink current (10µA)

Charger Status Outputs (FLG1, FLG2)

The MAX17703 features two open drain status output pins (FLG1 and FLG2) to indicate the status of the charger. Table $\underline{2}$ shows the status flag summary.

Table 2. Status Output Indications

CHARGER STATUS FLG (FLG2 and FLG1)	FLG2	FLG1	CHARGER STATE
11	Open drain in Hi- Impedance (1)	Open drain in Hi- Impedance (1)	Charger Off
10	Open drain in Hi- Impedance (1)	Open drain pulls low (0)	Charging in progress (precharge, CC, CV, or topup-charge states)
00	Open drain pulls low (0)	Open drain pulls low (0)	Full-battery state (charging complete)
01	Open drain pulls low (0)	Open drain in Hi- Impedance (1)	Latched fault or charge suspend due to high- or low-battery- temperature detection*

*Latched-fault state includes latched hardware faults and faulty battery states. Charge suspended due to high or low battery temperature is not a latched fault. <u>Table 3</u> provides various fault detection features available and their behaviors in MAX17703.

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

Table 3. Protection Under System Faults

FAULT CONDITION	FAULT MONITOR STATE	FAULT BEHAVIOR	
RT/SYNC to SGND/EP short			
GATEN to DCIN short		Latched Fault. Need to recycle power to restart the device.	
TMR unconnected	Power-Up Check		
TMR to SGND/EP short	Oneek		
V _{REF} to SGND/EP short	-		
V _{REF} < 1.95V or V _{REF} > 3.05V	Continuous,		
(V _{GATEN} - V _{DCIN}) < V _{GATEN_} OK	During Normal		
V_{FB} < 65mV (FB to SGND/EP short or R_{TOP} open fault)	Operation		
Faulty battery (timer count in Precharge state t _{TC} > t _{PCHG} , timer count in CC or CV state t _{TC} > t _{FCHG})	Precharge, CC, and CV States		
V _{DDTH} < 1.25V (V _{DDREF})	CV and Topup- Charge States		
High- or low-battery-temperature detection (V _{TEMP} < 1V (V _{TEMPL}) or V _{TEMP} > 1.5V (V _{TEMPU}))	Precharge, CC, CV, Topup- Charge States	Suspend Charge and Pause Timer. Upon entering back to an allowed operating temperature range, the timer resumes, charging resumes back to the previous state	

Linear Regulator (V_{CC} and EXTVCC)

The MAX17703 integrates two internal low-dropout (LDO) linear regulators INT-LDO and EXT-LDO that power V_{CC}. V_{CC} powers gate drivers and internal control circuitry. INT-LDO is powered from V_{IN} and turns on when V_{EN/UVLO} > V_{ENT} (0.7V). EXT-LDO is powered from EXTVCC. At any time, only one of these two linear regulators operates, depending on the EXTVCC voltage. If V_{EXTVCC} > 4.7V (typ) then V_{CC} is powered from EXT-LDO. If V_{EXTVCC} < 4.46V(typ), then V_{CC} is powered from INT-LDO. Powering V_{CC} from EXTVCC reduces on-chip power dissipation and increases efficiency at higher input voltages. Connect EXTVCC to V_{OUT} for applications with V_{OUT} ≥ 4.8V. The maximum voltage limit on EXTVCC is 24V. Bypass EXTVCC with a 1µF ceramic capacitor to SGND/EP. Leave EXTVCC open when not used. Bypass V_{CC} to PGND with at least a 4.7µF/0805, low-ESR ceramic capacitor.

Reference Voltage (VREF)

The MAX17703 provides a ±1.4% accurate 2.5V reference voltage on the V_{REF} pin. V_{REF} can be used to program V_{ILIM} to set the CC mode charging current (I_{CHGMAX}). V_{REF} can also be used to program TMR and TEMP for disabling the charger timer and setting the battery operating temperature range, respectively. Connect a minimum 0.1µF low-ESR ceramic capacitor between V_{REF} and SGND/EP. See the <u>CC Mode Charging Current Setting (ILIM)</u> and <u>Setting the Battery Operating Temperature Range (TEMP)</u> sections for more details.

Setting the Switching Frequency and External Clock Synchronization (RT/SYNC)

The switching frequency of the device can be programmed from 125kHz to 2.2MHz by using a resistor ($R_{RT/SYNC}$) connected from the RT/SYNC pin to SGND/EP. $R_{RT/SYNC}$ can be calculated using the following equation:

$$R_{\text{RT/SYNC}} = \frac{44830}{f_{\text{SW}}} - 1.205$$

Where $R_{RT/SYNC}$ is in k Ω and f_{SW} is in kHz. Leave the RT/SYNC pin unconnected to operate the device at 350kHz (default) switching frequency.

The MAX17703 can be synchronized to an external clock coupled to the RT/SYNC pin through a 10pF ceramic capacitor. The external clock is detected after checking the rising edge for 112 cycles of the internal clock (set by RT/SYNC). If the external clock frequency is within the allowed SYNC frequency range (\pm 10% of nominal internal clock frequency), the

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

device stops switching for 2 switching time periods and then restarts with an external clock. When the external clock is removed, the device stops switching for 10 switching time periods and then restarts with the internal clock.

The minimum external-clock pulse width should be greater than 100ns. The off-time duration of the external clock should be at least 100ns.

Peak Current-Limit

The MAX17703 provides a cycle-by-cycle overcurrent protection by limiting the peak current-sense voltage ($V_{CSP} - V_{CSN}$) across the current sense pins. When an overcurrent event (($V_{CSP} - V_{CSN}$) > V_{CS} _PEAK) is detected, the overcurrent comparator in the MAX17703 terminates the DH pulse and limits the peak current. The overcurrent fault is not latched.

Charging Current Monitoring (ISMON)

The output charge current can be monitored by observing the voltage at the ISMON pin. Connect a 1nF ceramic capacitor on ISMON to filter out the switching frequency component in the ISMON voltage. The charging current is given by the following equation:

$$I_{\rm CHG} = \frac{V_{\rm ISMON}}{30 \times R_{\rm S}}$$

where,

I_{CHG} = Charging current

V_{ISMON} = Voltage on the ISMON pin

R_S = Current-sense resistance

Thermal-Shutdown Protection

Thermal-shutdown protection limits the junction temperature of the device. When the junction temperature of the device exceeds +160°C, an on-chip thermal sensor shuts down the device, allowing the device to cool. The device turns on after the junction temperature reduces by 10°C. Carefully evaluate the total power dissipation (see the <u>Device Power</u> <u>Dissipation</u> section) to avoid unwanted triggering of the thermal shutdown during normal operation.

Applications Information

Inductor Selection

Three key inductor parameters must be specified for operation with the device: inductance value (L), DC resistance (R_{DCR}), and inductor saturation current (I_{SAT}).

The required inductance is calculated based on the inductor current ripple ratio (LIR), i.e., ratio of peak-to-peak ripple current (ΔI_L) to CC mode charging current (I_{CHGMAX}). A good compromise between size and loss is an LIR of 0.3.

The inductance value (L) is given by the higher value of the two calculated inductances:

$$L1 = \frac{V_{OUT^{X}}(1-D)}{LIR \times I_{CHGMAX} \times f_{SW}}$$

$$L2 = \frac{V_{OUT}}{LIR \times I_{CHGMAX} \times f_{SW}}$$

600000 × I_{CHGMAX}

where,

V_{OUT} = Desired voltage across the battery

I_{CHGMAX} = CC mode charging current

D = Duty cycle of the converter, V_{OUT}/V_{IN}

V_{IN} = Nominal input voltage

f_{SW} = Switching frequency in Hz

Select an inductor that is nearest to the calculated value. The inductor (RMS) current rating should be more than the CC mode charging current. Select a low-loss inductor with acceptable dimensions and the lowest possible DC resistance. The saturation current rating (I_{SAT}) of the inductor must be high enough to ensure that saturation can occur only above the overcurrent threshold corresponding to V_{CS PEAK}.

Output Capacitor Selection

Batteries have significant internal charging resistance and connection resistances (R_{BAT}). The switching ripple component of charger output current flows into R_{BAT} and results in a large output-voltage ripple.

To reduce the voltage ripple across the battery, additional X7R ceramic capacitors and/or low-ESR POSCAP capacitors can be used at the output of the charger. X7R ceramic output capacitors are preferred due to their stability over temperature. For higher values of output capacitance, low-ESR POSCAP capacitors can be used in parallel with ceramic capacitors.

Calculate the required output capacitance (C_{OUT}) based on the following equation:

$$C_{OUT} = \frac{25 \times I_{CHGMAX}}{f_{SW} \times V_{OUT}}$$

where:

I_{CHGMAX} = CC mode charging current setting

f_{SW} = Switching frequency in Hz

V_{OUT} = Desired voltage across the battery

Derating of ceramic capacitors with DC-bias voltage must be considered while selecting the capacitors, using the manufacturer data sheet. The selected output capacitor (C_{OUT_SEL}) and its equivalent series resistance (ESR_{COUT}) affect the output voltage ripple (ΔV_{OUT}). Estimate the resultant output-voltage ripple (ΔV_{OUT}) using the following equation:

$$\Delta V_{OUT} \approx \Delta I_L \times \left(\text{ESR}_{\text{COUT}} + \frac{1}{8 \times f_{\text{SW}} \times C_{\text{OUT}} \text{SEL}} \right)$$

where ΔI_L is the inductor peak-to-peak ripple current.

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

In applications with a long cable between the charger output and the battery, to dampen the oscillations caused by the interaction of the cable inductance with the low ESR output capacitors of the charger circuit, an electrolytic capacitor with appropriate ESR (equivalent series resistance) may be used. Choose an electrolytic capacitor equal to 1.5 times the value of C_{OUT_SEL} . Select an electrolytic capacitor with the an equivalent series resistance (ESR_{ELCO}) as calculated below:

$$\mathsf{ESR}_{\mathsf{ELCO}} = \sqrt{\frac{L_{\mathsf{CABLE}}}{C_{\mathsf{OUT}}}}$$

where L_{CABLE} is the output cable inductance.

Input Capacitor Selection

The input filter capacitor reduces peak currents drawn from the power source and reduces noise and voltage ripple on the input caused by the switching converter. Calculate the required input capacitance at V_{IN} (C_{VIN}) using the following

equation:
$$C_{VIN} = \frac{I_{CHGMAX} \times D \times (1 - D)}{\eta \times f_{SW} \times \Delta V_{IN}}$$

where:

D = $\frac{V_{OUT}}{V_{IN}}$ is the duty ratio of the converter

 f_{SW} = Switching frequency in Hz

 ΔV_{IN} = Allowable input-voltage ripple

 η = Efficiency of the converter

I_{CHGMAX} = CC mode charging current

Choose $\Delta V_{IN} \le 0.5V$ to minimize voltage ripple across the external nMOSFET and to provide robust operation during input short-circuit events.

The input capacitor RMS current (I_{RMS}) is calculated using the following equation:

$$I_{\rm RMS} = I_{\rm CHGMAX} \times \frac{\sqrt{V_{\rm OUT} \times (V_{\rm IN} - V_{\rm OUT})}}{V_{\rm IN}}$$

Choose low-ESR ceramic input capacitors that exhibit less than a 10°C temperature rise at I_{RMS} for optimal long-term reliability. X7R capacitors are recommended in industrial applications for their temperature stability. Derating of ceramic capacitors with DC-bias voltage must be considered while selecting the capacitors using the manufacturer data sheet.

Choose an electrolytic capacitor at DCIN to prevent the DCIN voltage from being less than -0.3V during input short events. An electrolytic capacitor also provides the damping for potential oscillations caused by inductance of the longer input power path and input ceramic capacitor (C_{VIN}). Additionally, if required, add a Schottky diode at DCIN in parallel with the electrolytic capacitor.

Operating Input-Voltage Range

The following equations are used to calculate the operating input voltage range for a given output voltage and CC mode charging current setting. The minimum operating input voltage on the DCIN pin is given by the higher value from the two calculated voltages:

$$V_{\text{DCIN}(\text{MIN1})} = \frac{V_{\text{OUT}} + I_{\text{CHGMAX}} \times \left(R_{\text{DS}} - ON(\text{LS}) + R_{\text{DCR}(\text{MAX})}\right)}{1 - \left(1.05 \times f_{\text{SW}} \times \left(t_{\text{DT}} - \text{HL} + t_{\text{MIN}} - ON_{\text{DL}}(\text{MAX})\right)\right)} + I_{\text{CHGMAX}} \times \left(R_{\text{DS}} - ON(\text{HS}) - R_{\text{DS}} - ON(\text{LS})\right)$$
$$V_{\text{DCIN}(\text{MIN2})} = \left(V_{\text{OUT}} + 2.1V\right)$$

where:

 $V_{DCIN(MIN1)}$, $V_{DCIN(MIN2)}$ = Minimum operating input voltages; the higher of the two values is the minimum operating input voltage, $V_{DCIN(MIN)}$

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

 V_{OUT} = Desired regulation voltage across the battery

I_{CHGMAX} = CC mode charging current setting

 f_{SW} = Switching frequency in Hz

 $R_{DCR(MAX)}$ = Worst-case DC resistance of the inductor in Ω

 $R_{DS_ON(HS)}$ and $R_{DS_ON(LS)}$ = Maximum on-state resistances of high-side and low-side MOSFETs in Ω , respectively t_{DT} HL = Dead time (30ns)

t_{MIN_ON_DL(MAX)} = Worst case DL minimum guaranteed on time (100ns)

The maximum operating input voltage on the DCIN pin is calculated as follows:

$$V_{\text{DCIN(MAX)}} = \frac{V_{\text{OUT}}}{1.05 \times f_{\text{SW}} \times f_{\text{MIN}} \text{ON}_{\text{DH}(\text{MAX})}}$$

where:

V_{DCIN(MAX)} = Maximum operating input voltage

t_{MIN ON DH(MAX)} = Worst case DH minimum guaranteed on time (100ns)

CC Mode Charging Current Setting (ILIM)

The CC mode charge current setting involves setting up a voltage on the ILIM pin (V_{ILIM}) and choice of current sense resistor R_S. Selection of R_S involves a trade-off between power loss and charging current accuracy. The best MAX17703 charging current accuracy is obtained with a voltage drop (V_{CSP} - V_{CSN}) of 50mV across R_S. (V_{CSP} - V_{CSN}) can be reduced at the expense of charging current accuracy to reduce power loss. The recommended range for voltage across R_S is 30mV (\pm 6.7% charging current accuracy) to 50mV (\pm 4% charging current accuracy). R_S can be calculated using the following equation:

$$R_{\rm S} \le \frac{\left(V_{\rm CSP} - V_{\rm CSN}\right)}{I_{\rm CHGMAX}}$$

Once R_S is selected, V_{ILIM} can be calculated using the following equation:

$V_{\rm ILIM} = 30 \times R_{\rm S} \times I_{\rm CHGMAX}$

A resistor divider from V_{REF} to SGND/EP can be used to program V_{ILIM} as shown in Figure 5. The resistor divider values are calculated as follows:

$$R_{\text{LIM1}} = 20 \times (V_{\text{REF}} - V_{\text{ILIM}}) k\Omega$$

$$R_{\text{LIM2}} = 20 \times V_{\text{ILIM}} k\Omega$$

The permitted voltage range for the V_{ILIM} setting is 0.9V to 1.5V. The MAX17703 can be set to the default I_{CHGMAX} setting corresponding to (V_{CSP} - V_{CSN}) = 50mV across R_S by connecting ILIM to V_{REF}.

Connect an R-C filter in the current-sense signal path as shown in Figure 5 to attenuate switching noise while preserving accuracy and bandwidth. Select an R-C filter corner frequency at 5 times the switching frequency. The recommended filter resistance (R1) is 40Ω for minimal impact on the current-sense accuracy. Place the filter close to the CSP and CSN pins of the device. Calculate the value of filter capacitor C1 using the following equation:

$$C1 = \frac{1}{2\pi x R 1 x 5 x f_{SW}}$$

where f_{SW} = Switching frequency in Hz

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

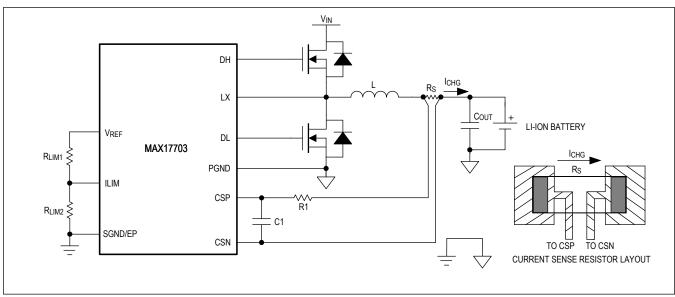


Figure 5. Current-Sense Circuit

Setting the Input Undervoltage-Lockout Level (EN/UVLO)

The MAX17703 offers an adjustable input undervoltage-lockout level using the EN/UVLO pin. Pulling the EN/UVLO pin below 1.09V (typ) stops charger operation. Pulling EN/UVLO below 0.64V (typ) causes the MAX17703 to shut down. In this state, the device draws I_{IN_SH} (7µA) quiescent current. *Figure 6* shows the recommended EN/UVLO configuration based on the required input-voltage range. Connect EN/UVLO to the center node of a resistor divider from the DCIN to SGND/EP to set the input voltage at which the device turns on. Choose R1 as follows:

 $R1 \leq (10000 \times V_{\text{DCIN(MIN)}})$

where $V_{DCIN(MIN)}$ is the voltage at which the device is required to turn on.

Calculate the value of R2 using the following equation:

$$R2 = \frac{V_{\text{EN}_{\text{TH}_{\text{R}}} \times R1}}{(V_{\text{DCIN(MIN)}} - V_{\text{EN}_{\text{TH}_{\text{R}}} + (I_{\text{EN}_{\text{F}}} - \text{BIAS} \times R1))}$$

where:

 $I_{EN-BIAS}$ = Internal bias pullup current on the EN/ULVO pin (3µA)

 V_{EN} TH R = EN/UVLO rising threshold voltage (1.25V)

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

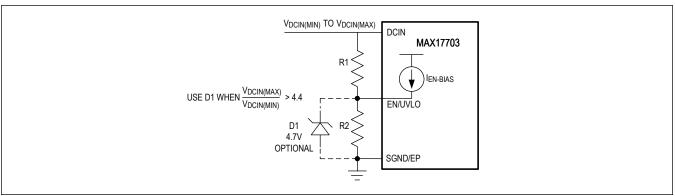


Figure 6. Setting the Input Undervoltage-Lockout

Current-Regulation Loop Compensation (COMP)

The MAX17703 features a COMP pin to tune the current loop to control performance of the average current-mode controller. Refer to Figure 1 for a depiction of the compensation network on the COMP pin using R_Z, C_Z, and C_P. The choice of the compensation component values depends on the chosen inductor (L) and its DC resistance (R_{DCR}), switching frequency (f_{SW}), current sense resistor (R_S), maximum operating input voltage (V_{DCIN(MAX)}), the desired regulation voltage across the battery (V_{OUT}), worst-case maximum battery charging resistance (R_{BAT}), the maximum on-resistances of the step-down converter nMOSFETs (R_{DS_ON(HS)} and R_{DS_ON(LS)}) and the maximum cabling and contact resistances (R_{CONNECTION}) in the charging path.

Calculate the compensation resistor R_Z using the following equation:

 $R_{Z} = \frac{3000 \times L \times f_{SW}}{V_{DCIN(MAX)} \times R_{S}}$

Calculate the compensation capacitor C_Z using the following equation:

 $C_Z = \frac{0.8 \times L}{R_Z \times R_E}$

where,

 $R_{E} = \left[R_{\text{DCR}} + R_{\text{S}} + R_{\text{DS} \text{ ON(HS)}} \times D_{\text{MIN}} + R_{\text{DS} \text{ ON(LS)}} \times (1 - D_{\text{MIN}}) + R_{\text{BAT}} + R_{\text{CONNECTION}} \right]$

$$D_{MIN} = \frac{V_{OUT}}{V_{DCIN(MAX)}}$$

Calculate the high-frequency pole capacitor (C_P) using the following equation:

 $C_{\mathsf{P}} = \frac{0.35}{R_Z \times f_{\mathsf{SW}}}$

Setting Output Voltage and Voltage Regulation Loop (FB)

The MAX17703 features a FB pin to regulate the voltage across the battery to a desired level. Connect a feedback resistor divider (R_{TOP} and R_{BOT}) with a compensating capacitor (C_{FB}) as depicted in <u>Figure 1</u>. The choice of feedback components depends on the desired regulation voltage across the battery (V_{OUT}), the chosen switching frequency (f_{SW}), and the operating input-voltage range ($V_{DCIN(MAX)}$ and $V_{DCIN(MIN)}$).

Calculate R_{TOP} and R_{BOT} using the following equations:

 R_{TOP} = 10 × V_{OUT} k Ω

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

$$R_{BOT} = \frac{R_{TOP}}{\left(\frac{V_{OUT}}{V_{FB_{REG}}} \cdot 1\right)} k\Omega$$

where V_{FB_REG} is the FB reference voltage. Calculate C_{FB} using the following equation:

$$C_{\rm FB} = \frac{1}{1.5 \times 10^6 \times R_{\rm PAR}}$$

where,

 $R_{\text{par}} = \frac{R_{\text{TOP}} \times R_{\text{BOT}}}{R_{\text{TOP}} + R_{\text{BOT}}}$ in k Ω .

Setting Battery Deep-Discharge Voltage Level (DDTH)

The MAX17703 offers a battery deep-discharge state detection mechanism through the DDTH pin. During power-up the device enters a precharge state when the voltage at the DDTH pin (V_{DDTH}) is less than 1.25V (V_{DDREF}). The device transitions into a CC state when V_{DDTH} exceeds V_{DDREF} . The deep-discharge voltage sense level of a battery can be set by connecting DDTH to the center node of a resistor-divider from output to SGND/EP as shown in Figure 1. Connect DDTH to V_{REF} when not used.

Select R_{DDT} in the range of $50k\Omega$ to $100k\Omega$.

Calculate resistor R_{DDB} from the following equation:

$$R_{DDB} = \frac{R_{DDT}}{\left(\frac{V_{OUTDD}}{V_{DDREF}} - 1\right)}$$

where,

 V_{OUTDD} = Deep-discharge level of the battery

V_{DDREF} = Deep-discharge detection comparator threshold (1.25V)

Setting the Battery Operating Temperature Range (TEMP)

The MAX17703 features a TEMP pin for battery temperature sensing and suspends charging when the temperature is out of the programmed operating temperature range using a negative temperature coefficient (NTC) resistor. Connect an NTC resistor to the TEMP pin along with a resistor divider from V_{REF} to SGND/EP as shown in Figure 7. A 47k Ω NTC resistor with B-constant (25°C - 85°C) = 4108 is recommended. Calculate R_{TEMP1} and R_{TEMP2} using the following equations:

 $R_{\text{TEMP1}} = \frac{\frac{1.25 \times R_{\text{NTCCOLD}} \times R_{\text{NTCHOT}}}{(R_{\text{NTCCOLD}} - 2.25 \times R_{\text{NTCHOT}})}$ $R_{\text{TEMP2}} = \frac{\frac{0.67 \times R_{\text{NTCCOLD}} \times R_{\text{TEMP1}}}{(R_{\text{NTCCOLD}} + R_{\text{TEMP1}})}$

Where $R_{NTCCOLD}$ is the resistance value of the selected NTC resistor at a low battery-operating temperature limit and R_{NTCHOT} is the resistance value of the selected NTC resistor at a high battery-operating temperature limit. To disable the battery temperature sensing feature, use $R_{TEMP1} = R_{TEMP2} = 100 k\Omega$

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

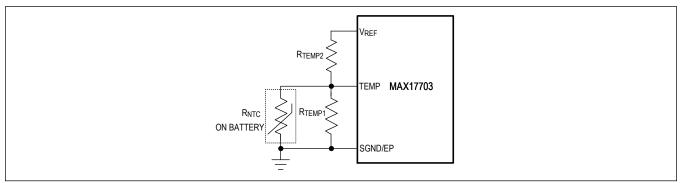


Figure 7. Setting the Battery Operating Temperature Range

Bootstrap Capacitor Selection

The bootstrap capacitance (C_{BST}) value is determined by the selection of the high-side nMOSFET(s). Choose C_{BST} using the following equation:

$$C_{BST} \ge \frac{\Delta Q_G}{\Delta V_{BST}}$$

where:

 ΔQ_G = Total gate charge of the high-side nMOSFET(s)

 ΔV_{BST} = Voltage variation allowed on the high-side nMOSFET(s) driver after turn-on

Choose $\Delta V_{BST} \le 100 \text{mV}$ to select C_{BST}. The bootstrap capacitor should be a low-ESR ceramic capacitor. A minimum value of 0.1μ F is recommended.

Bootstrap Diode Selection

Select a Schottky diode with the following ratings:

- Reverse voltage rating \geq (Maximum input operating voltage + 10V)
- Average forward current rating ≥ 1A

Choose a diode with low forward voltage drop and low reverse leakage current across the operating temperature range.

Input Short-Circuit Protection External nMOSFET Selection

The MAX17703 is designed to control an external logic-level nMOSFET that turns off in less than 100ns and isolates the V_{IN} node from input short-circuit events. This feature prevents discharge of the battery into the input during input short-circuit events. The external nMOSFET used for this feature only turns on once during power-up and turns off during shutdown and, therefore, does not need to be optimized for switching performance. Select an external nMOSFET with low R_{DS-ON} for low forward path conduction losses. The MAX17703 supports external nMOSFETs with gate charge up to 250nC at V_{GS} = 3.9V. Using larger gate charge values results in a gate charging time larger than t_{GATEN_OK} (15ms typ) and causes the MAX17703 to enter a latched-fault condition.

Step-Down Converter nMOSFET Selection

The MAX17703 drives two external logic-level nMOSFETs to implement the step-down converter high-side and low-side switches. These nMOSFETs must be logic-level compatible with guaranteed on-resistance specifications provided at V_{GS} = 4.5V. The key selection parameters to choose these MOSFETs include:

- On-resistance (R_{DS-ON})
- Maximum drain-to-source voltage (V_{DS(MAX)})
- Miller Plateau voltage on the nMOSFET Gaté (V_{MIL})
- Total gate charge (Q_G)

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

- Output capacitance (C_{OSS})
- Power-dissipation rating and package thermal resistance
- Maximum operating junction temperature

For the step-down converter, nMOSFETs should be chosen in such a way that the switching losses and conduction losses are balanced and optimized. The duty cycles for the high-side and low-side external nMOSFETs can be calculated as follows:

$$D = \frac{V_{OUT}}{V_{IN}}$$

High-side nMOSFET duty cycle: D

Low-side nMOSFET duty cycle: 1 - D

High-side nMOSFET losses can be estimated using the following formula:

PHS-MOSFET = PHS-MOSFET_CONDUCTION + PHS-MOSFET_SWITCHING

 $P_{HS} - MOSFET_CONDUCTION = I_{CHG}^2 \times R_{DS} - ON(HS) \times D$

$$\mathsf{P}_{\mathsf{HS}-\mathsf{MOSFET}_{\mathsf{SWITCHING}}} = f_{\mathsf{SW}} \times \left(\left[\frac{V_{\mathsf{IN}} \times I_{\mathsf{CHG}}}{2} \times \frac{Q_{\mathsf{SW}} \times R_{\mathsf{DR}}}{V_{\mathsf{CC}} - V_{\mathsf{MIL}}} \right] + \left[V_{\mathsf{IN}} \times Q_{\mathsf{rr}} \right] + \left[\frac{1}{2} \times C_{\mathsf{OSSHS}} \times V_{\mathsf{IN}}^2 \right] + \left[\frac{1}{2} \times C_{\mathsf{OSSLS}} \times V_{\mathsf{IN}}^2 \right] \right)$$

where,

f_{SW} = Switching frequency in Hz

I_{CHG} = Charging current

 Q_{SW} = Switching charge of the high-side nMOSFET from the nMOSFET data sheet,

R_{DR} = Sum of the DH pin driver pullup resistance and the high-side nMOSFET internal gate resistance,

 $V_{MIL} = V_{GS}$ of the high-side nMOSFET that corresponds to $I_D = I_{CHGMAX}$ on the V_{GS} vs. I_D curve in the nMOSFET data sheet

Q_{rr} = Reverse-recovery charge of low-side nMOSFET(s) body diode

C_{OSSHS} = Effective output capacitance of the high-side nMOSFET(s)

C_{OSSLS} = Effective output capacitance of the low-side nMOSFET(s)

Low-side nMOSFET losses can be estimated using the following formula:

$$P_{LS-MOSFET} = I_{CHG}^{2} \times R_{DS-ON(LS)} \times (1 - D) + V_{D} \times I_{CHG} \times t_{DT} \times f_{SW} \times 2$$

where,

 V_D = Forward-drop of the low-side nMOSFET(s) body diode

t_{DT} = Dead time (30ns)

Take R_{DS-ON} variation with respect to temperature into account while calculating the power losses and ensure that the losses of each nMOSFET do not exceed their power rating and operate within a safe junction temperature rating. When parallel nMOSFETs are used, it is recommended to use appropriate independent series gate resistors for each nMOSFET to account for gate charge variation from one nMOSFET to another.

System Considerations

The MAX17703 is designed to charge Li-ion batteries. When load current is drawn during the battery charging process, the charging current available for battery charging reduces. This influences the overall charging time period in CC and CV states. The safety timer period (T_{FCHG}) must be adjusted accordingly. Disable the timer function to charge the Li-ion batteries with parallel system load current equal to or greater than taper current threshold (I_{TCHG}), to avoid undesired latched-fault in CC or CV states.

For safe operation, follow the procedure below while making connections:

- 1. Connect the battery terminals to the output of the charger circuit. Note that the output capacitors of the charger can draw current from the battery during a hot plug-in/connection process.
- 2. Connect the input power source to the battery charger circuit only after securely connecting the battery at the output.

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

3. Do not operate the charger without battery.

Device Power Dissipation

The MAX17703 must dissipate losses due to quiescent-current consumption and the internal gate driver.

If V_{CC} is powered from V_{IN}, use the following equation to calculate the approximate IC losses:

 $\mathsf{P}_{\mathsf{MAX17703}} = V_{\mathsf{IN}} \times \left[\left[\mathsf{Q}_{G} \times \mathsf{f}_{\mathsf{SW}} \right] + \mathsf{I}_{\mathsf{QNS}} \right]$

When V_{OUT} is used to power V_{CC} by connecting the EXTVCC pin to an output voltage greater than 4.8V, use the following equation to calculate the approximate IC losses:

$$\mathsf{P}_{\mathsf{MAX17703}} = \mathsf{V}_{\mathsf{EXTVCC}} \times \left[\left[\mathsf{Q}_{G} \times \mathsf{f}_{\mathsf{SW}} \right] + \mathsf{I}_{\mathsf{QNS}} \right]$$

where,

 Q_G = Total gate charge of high-side and low-side nMOSFETs,

I_{QNS} = Input Quiescent current (2.1mA)

f_{SW} = Switching Frequency in Hz

Calculate the junction temperature using the following equation and ensure that it does not exceed +125°C.

$$T_J = T_{A(MAX)} + (\theta_{JA} \times P_{MAX17703})$$

where,

 T_J = Junction temperature

 $P_{MAX17703}$ = Power loss in the device

 θ_{JA} = Junction-to-ambient thermal resistance

T_{A(MAX)} = Maximum ambient temperature

PCB Layout Guidelines

Careful PCB layout is critical to achieve low losses, and low EMI emissions. Use the following guidelines for PCB layout:

- Place ceramic input filter capacitors as close as possible across the drain of the high-side nMOSFET and source of the low-side nMOSFET.
- Use Kelvin connections and route the V_{IN} and DCIN traces from input short-circuit protection nMOSFET source and drain terminals as a differential pair and connect to V_{IN} and DCIN pins of the device. Place V_{IN} and DCIN bypass capacitors close to V_{IN} and DCIN pins respectively.
- Place V_{CC} and EXTVCC bypass capacitors and the BST capacitor near the respective pins.
- Place GATEN-to-DCIN bypass capacitor close to the GATEN, DCIN pins of the device.
- Place bootstrap capacitor close to BST, LX pins of the device.
- Route the bootstrap diode connections from V_{CC} capacitor and to bootstrap capacitor as short as possible to minimize the loop inductance.
- Route switching traces (BST, LX, DH, and DL) away from sensitive signal traces (RT/SYNC, COMP, CSP, CSN, and FB).
- The gate current traces must be short in length. Use multiple vias to route these signals if routed from one layer of the PCB to another layer.
- Route current-sense traces as a differential pair to minimize the loop inductance and avoid differential noise.
- Place the current-sense filter resistor and capacitor near both the CSP and CSN pins.
- Place feedback and compensation components close to the device and connect to the SGND/EP copper area.
- Place all power components on the top side of the board and run the power-stage currents using traces or copper fills on the top side only, without adding vias, wherever possible.
- Keep the power traces and load connections short. Use multilayer, thick copper PCBs (2oz or higher) to enhance efficiency and minimize trace inductance and resistance.
- Allocate a large PGND copper area for the output node, and connect the return terminals of the input filter capacitors, output capacitors, and the source terminals of the low-side nMOSFET(s) to that area.

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

• Refer to the MAX17703 EV kit data sheet for recommended PCB layout and routing.

Typical Application Circuit

10A Li-Ion Battery Charger

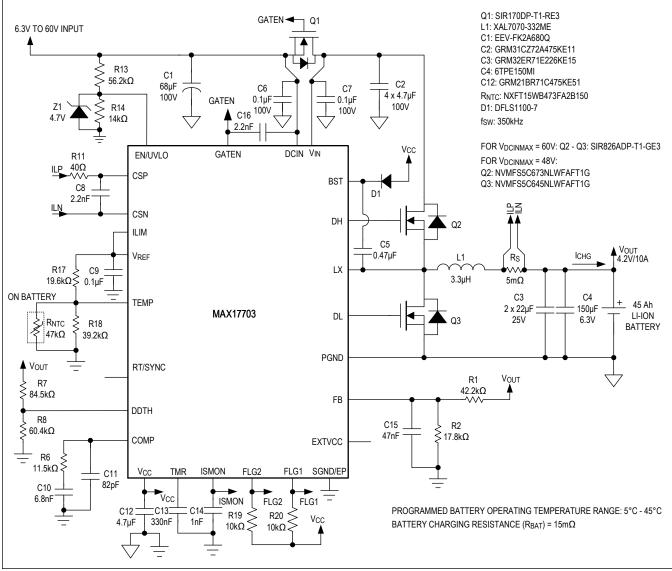


Figure 8. 4.2V/10A Li-Ion Battery Charger

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

Ordering Information

PART NUMBER	TEMPERATURE RANGE	PIN-PACKAGE	
MAX17703ATG+	-40°C to +125°C	24 TQFN-EP	
MAX17703ATG+T	-40°C to +125°C	24 TQFN-EP	

+ Denotes a lead(Pb)-free/RoHS-compliant package.

T = Tape-and-reel.

4.5V to 60V, Synchronous Step-Down Li-Ion Battery Charger Controller

Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	4/21	Release for Market Intro	—
1	12/21	Updated Benefits and Features, Electrical Characteristics, Typical Operating Characteristics TOC1, TOC2, TOC3, TOC5, TOC14, Pin Description, Input Short- Circuit Protection (GATEN), Inductor Selection, Output Capacitor Selection, Operating Input-Voltage Range, CC Mode Charging Current Setting (ILIM), Setting the Input Undervoltage-Lockout Level (EN/UVLO), Current-Regulation Loop Compensation (COMP), Setting Output Voltage and Voltage Regulation Loop (FB), Setting the Battery Operating Temperature Range (TEMP), Step-Down Converter nMOSFET Selection, Device Power Dissipation, PCB Layout Guidelines, and Typical Application Circuit, 10A Li-Ion Battery Charger sections	5, 8–9, 11, 18, 22-27, 29-31



Information furnished by Analog Devices is believed to be accurate and reliable. However, no responsibility is assumed by Analog Devices for its use, nor for any infringements of patents or other rights of third parties that may result from its use. Specifications subject to change without notice. No license is granted by implication or otherwise under any patent or patent rights of Analog Devices. Trademarks and registered trademarks are the property of their respective owners.