## 72V, 1A, Automotive Synchronous Step-Down DC-DC Converter

### **General Description**

The MAX20059 is a high-efficiency, high-voltage, synchronous step-down DC-DC converter IC with integrated MOSFETs that operates over a 4.5V to 72V input. The converters can deliver up to 1A current. Output voltage is programmable from 0.8V to 90%V<sub>IN</sub>. The feedback voltage-regulation accuracy over -40°C to +125°C is  $\pm$ 1.5%.

The IC features a peak-current-mode-control architecture and can be operated in the pulse-width modulation (PWM) or pulse-frequency modulation (PFM) control schemes.

The IC is available in a 12-pin ( $3mm \times 3mm$ ) side-wettable TDFN package with an exposed pad for thermal heat dissipation.

### **Applications**

- 48V Systems
- Mild Hybrid Applications

Ordering Information appears at end of data sheet.

### **Benefits and Features**

- Synchronous DC-DC Converters with Integrated FETs
  - 72V Input for 48V Systems
  - Internal Compensation
- Flexibility
  - Output Adjustable from 0.8V to 90%VIN
  - 200kHz to 2200kHz Adjustable Frequency with External Clock Synchronization
  - Programmable Peak Current Limit (1.14A or 1.6A)
- RESET Output and EN Input (26V max) Simplify Power Sequencing
- Protection Features and Operating Range Ideal for Automotive Applications
  - Programmable EN/UVLO Threshold
  - · Adjustable Soft-Start and Prebiased Power-Up
  - Thermal Shutdown
  - -40°C to +125°C Automotive Temperature Range
  - AEC-Q100 Qualified



## 72V, 1A, Automotive Synchronous Step-Down DC-DC Converter

## **Absolute Maximum Ratings**

V <sub>IN</sub> to SGND	0.3V to +80V
EN/UVLO to SGND	0.3V to +26V
EXTVCC to SGND	0.3V to +14V
LX to PGND	0.3V to V <sub>IN</sub> + 0.3V
FB, SS, MODE/ILIM,	
RT/SYNC to SGND	0.3V to V <sub>CC</sub> + 0.3V
PGND to SGND	0.3V to +0.3V
LX Total RMS Current	±1.2A
RESET, V <sub>CC</sub> to SGND	0.3V to +6V

Continuous Power Dissipation ( $T_A = +70^{\circ}C$ )	
(Multilayer board	
derate 24.4mW/°C above +70°C)	1951.2mW
Operating Temperature Range	-40°C to +125°C
Junction Temperature	+150°C
Storage Temperature Range	-65°C to +150°C
Lead Temperature (soldering, 10s)	+300°C
Soldering Temperature (reflow)	+260°C
ESD Protection (Human Body Model)	±2kV

## **Package Information**

### 12 SW TDFN-EP

Package Code	TD1233Y+2			
Outline Number	21-100176			
Land Pattern Number	90-100072			
Thermal Resistance, Four-Layer Board:				
Junction to Ambient ( $\theta_{JA}$ )	41°C/W			
Junction to Case (θ <sub>JC</sub> )	8.5°C/W			

For the latest package outline information and land patterns (footprints), go to <u>www.maximintegrated.com/packages</u>. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to www.maximintegrated.com/thermal-tutorial.

## 72V, 1A, Automotive Synchronous Step-Down DC-DC Converter

## **Electrical Characteristics**

 $(V_{IN} = 48V, V_{EN/UVLO} = open, R_{RT} = 105k\Omega, LX = open, T_A = T_J = -40^{\circ}C$  to +125°C, unless otherwise noted.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Input Voltage Range	V <sub>IN</sub>		4.5		72	V
Input Shutdown Current	I <sub>IN-SH</sub>	V <sub>EN</sub> = 0V, shutdown mode	2.5	7	13	μA
Input Quiescent Current	I <sub>Q_PFM</sub>	$R_{ILIM}$ = open or 422k $\Omega$		90		μA
	I <sub>Q_PWM</sub>	$R_{ILIM} = 243k\Omega$ or $121k\Omega$	2.5	4	6	mA
ENABLE/UVLO (EN)						
	V <sub>ENR</sub>	V <sub>EN/UVLO</sub> rising	1.19	1.215	1.24	
EN Threshold	V <sub>ENF</sub>	V <sub>EN/UVLO</sub> falling	1.09	1.115	1.14	V
	V <sub>EN-TRUESD</sub>	V <sub>EN/UVLO</sub> falling, true shutdown		0.7		
EN Pullup Current	I <sub>EN</sub>	V <sub>EN/UVLO</sub> = 1.215V	2.2	2.5	2.8	μA
LDO (V <sub>CC</sub> )						
Output Voltage Range	V <sub>CC</sub>	6V < V <sub>IN</sub> < 72V, 0mA < I <sub>VCC</sub> < 5mA	4.75	5	5.25	V
Current Limit	I <sub>VCC-MAX</sub>	V <sub>CC</sub> = 4.3V, V <sub>IN</sub> = 12V	12	28	52	mA
Dropout	V <sub>CC-DO</sub>	V <sub>IN</sub> = 4.5V, I <sub>VCC</sub> = 5mA			0.3	V
184.0	V <sub>CC-UVR</sub>	V <sub>CC</sub> rising	4.05	4.2	4.35	V
	V <sub>CC-UVF</sub>	V <sub>CC</sub> falling	3.65	3.8	3.95	V
EXT LDO (EXTVCC)						
Switchover Threshold		EXTVCC rising	4.65	4.74	4.88	V
Switchover-Threshold Hysteresis				0.3		V
Dropout	EXTVCC-DO	V <sub>EXTVCC</sub> = 4.75V, I <sub>VCC</sub> = 5mA			0.1	V
Current Limit		V <sub>CC</sub> = 4.3V, V <sub>EXTVCC</sub> = 5V	15	21	34	mA
POWER MOSFETs						
High-Side pMOS On-Resistance	R <sub>DS-ONH</sub>	I <sub>LX</sub> = 0.3A, sourcing		1.01	1.8	Ω
Low-Side nMOS On-Resistance	R <sub>DS-ONL</sub>	I <sub>LX</sub> = 0.3A, sinking		0.275	0.55	Ω
LX Leakage Current		T <sub>A</sub> = +25°C			2	μA
SOFT-START						
Charging Current	I <sub>SS</sub>		4.7	5	5.3	μA

## 72V, 1A, Automotive Synchronous Step-Down DC-DC Converter

## **Electrical Characteristics (continued)**

 $(V_{IN} = 48V, V_{EN/UVLO} = open, R_{RT} = 105k\Omega, LX = open, T_A = T_J = -40^{\circ}C$  to +125°C, unless otherwise noted.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
FEEDBACK (FB)						
		$R_{ILIM} = 243k\Omega \text{ or } 121k\Omega$	0.788	0.8	0.812	V
FB Regulation voltage	VFB	$R_{ILIM}$ = open or 422k $\Omega$	0.788	0.812	0.824	V
FB Input Leakage Current		V <sub>FB</sub> = 1V, T <sub>A</sub> = +25°C	-100		+100	nA
CURRENT LIMIT		·				
Book Current Limit Threshold	ISOURCE-	$R_{ILIM}$ = open or 243k $\Omega$	1.4	1.6	2.0	_
	LIMIT	$R_{ILIM} = 121k\Omega \text{ or } 422k\Omega$	0.94	1.14	1.36	
		$R_{ILIM}$ = open or 422k $\Omega$		7		mA
Negative Current-Limit	I <sub>SINK-LIMIT</sub>	$R_{ILIM} = 243k\Omega$	0.57	0.65	0.725	_
		R <sub>ILIM</sub> = 121kΩ	0.35	0.455	0.56	A
PEM Current Level	IDEM	R <sub>ILIM</sub> = open	0.2	0.33	0.48	_
		R <sub>ILIM</sub> = 422kΩ	0.1	0.22	0.344	
MODE						
MODE PFM Threshold		Rising	1	1.26	1.5	V
Hysteresis				0.19		V
TIMINGS						
Minimum On-Time	t <sub>ON-MIN</sub>		45	76	130	ns
Maximum Duty Cycle	DMAX		89	93	97	%
OSCILLATOR						
		R <sub>RT</sub> = 210kΩ	180	200	220	
		R <sub>RT</sub> = 140kΩ	270	300	330	
Switching Frequency	fsw	R <sub>RT</sub> = 105kΩ	360	400	440	
		R <sub>RT</sub> = 69.8kΩ	540	600	660	
		R <sub>RT</sub> = 19.1kΩ	1800	2033	2200	
SYNC Input Frequency			1.15 x		1.4 x	kHz
per R <sub>RT</sub>			fsw		<sup>t</sup> SW	
SYNC Input Frequency Range			220		2200	KHZ
Off-Time		SYNC pulse must exceed this number	40			ns
SYNC High Threshold	V <sub>SYNC-H</sub>		1	1.26	1.5	V
SYNC Hysteresis	V <sub>SYNC-HYS</sub>			0.18		V
Number of SYNC Pulses to Enable Synchronization		(Note 2)		1		Cycle

## 72V, 1A, Automotive Synchronous Step-Down DC-DC Converter

## **Electrical Characteristics (continued)**

 $(V_{IN} = 48V, V_{EN/UVLO} = open, R_{RT} = 105k\Omega, LX = open, T_A = T_J = -40^{\circ}C$  to +125°C, unless otherwise noted.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
RESET			~			
UV Threshold Rising		V <sub>FB</sub> rising		95		%
UV Threshold Falling		V <sub>FB</sub> falling		92		%
Delay After FB Reaches 95% Regulation				2.1		ms
Output Low Level		I <sub>RESET</sub> = 1mA			0.09	V
Output Leakage Current		T <sub>A</sub> = +25°C			1	μA
THERMAL SHUTDOWN						
Thermal-Shutdown Threshold		Temperature rising (Note 2)		+160		°C
Hysteresis		(Note 2)		20		°C

Note 1: All limits are 100% tested at +25°C. Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Typical values are at  $T_A = +25^{\circ}C$ .

**Note 2:** Guaranteed by design, not production tested.

## 72V, 1A, Automotive Synchronous Step-Down DC-DC Converter

## **Typical Operating Characteristics**

 $(T_A = +25^{\circ}C, unless otherwise noted.)$ 















## 72V, 1A, Automotive Synchronous Step-Down DC-DC Converter

## **Typical Operating Characteristics (continued)**

(TA = +25°C, unless otherwise noted.)















#### SOFT-START/SHUTDOWN FROM EN FPWM MODE (500mA LOAD)



## 72V, 1A, Automotive Synchronous Step-Down DC-DC Converter

## **Typical Operating Characteristics (continued)**

(T<sub>A</sub> = +25°C, unless otherwise noted.)













## 72V, 1A, Automotive Synchronous Step-Down DC-DC Converter

## **Pin Configuration**



## **Pin Description**

PIN	NAME	FUNCTION
1	PGND	Power Ground of the Converter. Connect externally to the power ground plane. Connect the SGND and PGND pins together at the ground return path of the $V_{CC}$ bypass capacitor.
2	V <sub>IN</sub>	Power-Supply Input. 4.5V to 72V input supply range. Decouple to PGND with a 2.2 $\mu$ F capacitor; place the capacitor close to the V <sub>IN</sub> and PGND pins.
3	V <sub>CC</sub>	$5V$ LDO Output. Bypass $V_{CC}$ with $1\mu F$ ceramic capacitance to SGND. This LDO is intended to power internal circuits only.
4	EN/UVLO	Enable/Undervoltage Lockout. Drive EN/UVLO high to enable the output. Connect to the center of the resistor-divider between $V_{\rm IN}$ and SGND to set the input voltage at which the part turns on. Leave the pin unconnected for always-on operation.
5	RESET	Open-Drain $\overrightarrow{\text{RESET}}$ Output. The $\overrightarrow{\text{RESET}}$ output is driven low if FB drops below 92% of its set value. RESET goes high 2.1ms after FB rises above 95% of its set value.
6	RT/SYNC	Frequency-Set and Synchronization. Connect a resistor from RT/SYNC to SGND to set the switching frequency of the part between 200kHz and 2000kHz. An external clock can be connected to the RT/SYNC pin to synchronize the part with an external frequency up to 2200kHz.
7	EXTVCC	External Power-Supply Input for the Internal LDO
8	FB	Feedback Input. Connect FB to the center tap of an external resistor-divider from the output to SGND to set the output voltage.
9	SS	Soft-Start Input. Connect a capacitor from SS to SGND to set the soft-start time.
10	MODE/ILIM	Mode and Current-Limit Set. Connect a resistor from MODE/ILIM to SGND to program the peak and runaway current limits and mode of operation of the part. See the <i>Current Limit and Mode of Operation Selection</i> section for more details.
11	SGND	Analog Ground
12	LX	Switching Node. Connect the LX pin to the switching side of the inductor.
_	EP	Exposed Pad. Connect EP to the SGND pin. Connect to a large copper plane below the IC to improve heat-dissipation capability. Add thermal vias below the exposed pad.

## 72V, 1A, Automotive Synchronous Step-Down DC-DC Converter



## **Functional Diagram**

## 72V, 1A, Automotive Synchronous Step-Down DC-DC Converter

### **Detailed Description**

The MAX20059 high-efficiency, high-voltage, step-down DC-DC regulator IC operates from 4.5V to 72V and delivers up to 1A load current. Feedback voltage-regulation accuracy meets  $\pm 1.5\%$  over load, line, and temperature.

The IC uses a peak-current-mode-control scheme. An internal transconductance error amplifier generates an integrated error voltage. The error voltage sets the duty cycle using a PWM comparator, a high-side current-sense amplifier, and a slope-compensation generator.

At each rising edge of the clock, the high-side MOSFET turns on and remains on until either the appropriate or maximum duty cycle is reached, or the peak current limit is detected.

During the high-side MOSFET's on-time, the inductor current ramps up. During the second half of the switching cycle, the high-side MOSFET turns off and the low-side MOSFET turns on and remains on until either the next rising edge of the clock arrives or sink-current limit is detected. The inductor releases the stored energy as its current ramps down, and provides current to the output. The internal low  $R_{DS(ON)}$  pMOS/nMOS switches ensure high efficiency at full load.

The IC also integrates a switching-frequency selector pin, a current-limit and mode-of-operation selector pin, an enable/undervoltage lockout (EN/UVLO) pin, programmable soft-start pin, and an open-drain RESET signal.

### **Current Limit and Mode of Operation**

Table 1 lists the value of the resistors to program PWM or PFM modes of operation and 1.6A or 1.14A peak current limits.

The mode of operation cannot be changed on the fly after power-up.

R <sub>ILIM</sub> (kΩ)	PEAK CURRENT LIMIT (A)	MODE OF OPERATION			
Open	1.6	PFM			
422	1.14	PFM			
243	1.6	PWM			
121	1.14	PWM			

### Table 1. R<sub>ILIM</sub> Settings

### **PWM Mode Operation**

In PWM mode, the inductor current can go negative. PWM operation provides constant frequency operation at all loads, and is useful in applications sensitive to switching frequency. However, the PWM mode of operation gives lower efficiency at light loads compared to the PFM mode of operation.

### **PFM Mode Operation**

PFM mode of operation disables negative inductor current and additionally skips pulses at light loads for high efficiency. In PFM mode, the inductor current is forced to a fixed peak every clock cycle until the output rises to 102% of the nominal voltage by monitoring the FB pin. Resistor tolerance impacts actual output voltage. Once the output reaches 102% of the nominal voltage, both the high-side and low-side FETs are turned off and the device enters hibernate operation until the load discharges the output to 101% of the nominal voltage. Most of the internal blocks are turned off in hibernate operation to save quiescent current. After the output falls below 101% of the nominal voltage, the device comes out of hibernate operation, turns on all internal blocks, and again commences delivering pulses of energy to the output until it reaches 102% of the nominal output voltage.

The advantage of the PFM mode is higher efficiency at light loads due to lower quiescent current drawn from supply. However, the output-voltage ripple is higher compared to PWM mode of operation, and switching frequency is not constant at light loads.

### Linear Regulator (V<sub>CC</sub>)

The IC has two internal low-dropout regulators (LDOs) that power V<sub>CC</sub>. One LDO is powered from the input voltage and the other LDO is powered from the EXTVCC pin. Only one of the two LDOs is in operation at a time, depending on the voltage levels present at the EXTVCC pin.

If EXTVCC rises above 4.74V (typ), V<sub>CC</sub> is powered from the EXTVCC pin. If EXTVCC falls below 4.44V (typ), V<sub>CC</sub> is powered from the input voltage. Powering V<sub>CC</sub> from EXTVCC increases efficiency, particularly at higher input voltages. Typical V<sub>CC</sub> output voltage is 5V. Bypass V<sub>CC</sub> to SGND with a 1 $\mu$ F capacitor.

When V<sub>CC</sub> falls below its undervoltage lockout (3.8V, typ), the internal step-down controller is turned off, and LX switching is disabled. The LX switching is re-enabled when the V<sub>CC</sub> voltage exceeds 4.2V (typ). The 400mV (typ) hysteresis prevents chattering on power-up and power-down.

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When powering EXTVCC from V<sub>OUT</sub>, an R-C network should be placed in the path to protect the LDO from a potential negative voltage transient due to a short-circuit event. A 4.7 $\Omega$  resistor and a 0.1 $\mu$ F capacitor is recommended (see the *Typical Application Circuit*).

## Switching-Frequency Selection and External Frequency Synchronization

The RT/SYNC pin programs the switching frequency of the converter. Connect a resistor from RT/SYNC to SGND to set the switching frequency of the part at any one of five discrete frequencies: 200kHz, 300kHz, 400kHz, 600kHz, or 2MHz (see Table 2 for resistor values).

The internal oscillator of the device can be synchronized to an external clock signal on the RT/SYNC pin. The external synchronization clock frequency must be between 1.15 x f<sub>SW</sub> and 1.4 x f<sub>SW</sub>, where f<sub>SW</sub> is the frequency programmed by the resistor connected from the RT/SYNC pin.

### **Operating Input Voltage Range**

The minimum and maximum operating input voltages for a given output voltage should be calculated as shown in the following equation:

### **Equation 1:**

$$\begin{split} V_{\text{IN(MIN)}} = & \frac{V_{\text{OUT}} + \left(I_{\text{OUT}(\text{MAX})} \times (R_{\text{DCR}} + 0.55)\right)}{D_{\text{MAX}}} + \left(I_{\text{OUT}(\text{MAX})} \times 1.25\right) \\ & V_{\text{IN}(\text{MAX})} = \frac{V_{\text{OUT}}}{f_{\text{SW}(\text{MAX})} \times t_{\text{ON}(\text{MIN})}} \end{split}$$

where V<sub>OUT</sub> is the steady-state output voltage, I<sub>OUT(MAX)</sub> is the maximum load current, R<sub>DCR</sub> is the DC resistance of the inductor, D<sub>MAX</sub> is the maximum allowable duty ratio (0.89), f<sub>SW(MAX)</sub> is the maximum switching frequency, and t<sub>ON(MIN)</sub> is the worst-case minimum switch on-time (120ns).

# RT/SYNC RESISTOR VALUE (kΩ) SWITCHING FREQUENCY (kHz) 210 200 140 300 105 400 69.8 600 19.1 2000

### Table 2. RT/SYNC Resistor Settings

### **Overcurrent Protection**

The IC is provided with a robust overcurrent-protection scheme that protects the IC under overload and output short-circuit conditions. The positive current limit is triggered when the peak value of the inductor current hits a fixed threshold (ILIM\_P, 1.6A/1.14A). At this point, the high-side switch is turned off and the low-side switch is turned on. The low-side switch is kept on until the inductor current discharges below 0.7 x ILIM\_P.

While in the PWM mode of operation, the negative current limit is triggered when the valley value of the inductor current hits a fixed threshold (ILIM\_N, -0.65A/-0.455A, depending on the value of the resistor connected to the MODE/ILIM pin). At this point, the low-side switch is turned off and the high-side switch is turned on.

### **RESET** Output

The IC includes a RESET pin to monitor the output voltage. The open-drain RESET output requires an external pullup resistor. RESET goes high (high impedance) in 2.1ms after the output voltage increases above 95% of the nominal voltage. RESET goes low when the output voltage drops to below 92% of the nominal voltage. RESET also goes low during thermal shutdown.

### **Thermal-Shutdown Protection**

The IC features thermal-overload protection and turns off when the junction temperature exceeds  $+160^{\circ}C$  (typ). Once the device cools by  $20^{\circ}C$  (typ), it turns back on with a soft-start sequence.

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### **Applications Information**

### Inductor Selection

Three key inductor parameters must be specified for operation with the device: inductance value (L), inductor saturation current (ISAT), and DC resistance (RDCR). To select inductor value, the ratio of inductor peak-to-peak AC current to DC average current (LIR) must be selected first. A good compromise between size and loss is a 30% peak-to-peak ripple current to average-current ratio (LIR = 0.3). The switching frequency, input voltage, output voltage, and selected LIR then determine the inductor value as follows:

$$L_{MIN1} = \frac{[V_{IN} - V_{OUT}] \times V_{OUT}}{V_{IN} \times f_{SW} \times I_{OUT} \times LIR}$$

where V<sub>OUT</sub>, I<sub>OUT</sub>, and f<sub>SW</sub> are nominal values. Select a low-loss inductor closest to the calculated value with acceptable dimensions and the lowest possible DC resistance. The saturation current rating (ISAT) of the inductor must be high enough to ensure that saturation occurs only above the peak current-limit value.

The next equation ensures that the internal compensating slope is greater than 50% of the inductor current down slope:

$$m \geq \frac{m_2}{2}$$

where m is the internal compensating slope and  $m_2$  is the sensed inductor current downslope as follows:

$$m_2 = \frac{V_{OUT} \times R_i}{L}$$

Here m is the internal slope compensation with the value in <u>Table 3</u>,  $m_2$  is the inductor current downslope, and  $R_i$  is the current-sense gain of 0.5 (typ).

Solving for L and adding 1.5 multiplier to account for tolerances in the system:

$$L_{MIN2} = \frac{V_{OUT} \times R_i \times 1.5}{2 \times m}$$

# Table 3. Internal Slope Compensation VSSwitching Frequency

SWITCHING FREQUENCY (kHz)	INTERNAL SLOPE COMPENSATION <i>m</i> (v/µs)
200	0.03676
300	0.05514
400	0.07576
600	0.11364
2000	0.3676

Select the larger of L<sub>MIN1</sub> and L<sub>MIN2</sub> as L<sub>MIN</sub>.

$$L_{MIN} = max(L_{MIN1}, L_{MIN2})$$

The maximum nominal inductor value recommended is 2 times the chosen value from the above formula:

$$L_{MAX} = 2 \times L_{MIN}$$

Select a nominal inductor value based on the following formula:

$$L_{MIN} < L_{NOM} < L_{MAX}$$

The best choice of inductor is usually the standard inductor value closest to  $L_{NOM}$ .

### Input Capacitor Selection

A low-ESR ceramic input capacitor of 4.7µF is recommended for proper device operation. This value can be adjusted based on application input-voltage-ripple requirements.

The discontinuous input current of the buck converter causes large input ripple current. The switching frequency, peak inductor current, and allowable peak-to-peak input-voltage ripple dictate the input-capacitance requirement. Increasing the switching frequency or the inductor value lowers the peak-to-average current ratio, yielding a lower input-capacitance requirement.

The input ripple comprises  $\Delta V_Q$  (caused by the capacitor discharge) and  $\Delta V_{ESR}$  (caused by the ESR of the input capacitor). The total voltage ripple is the sum of  $\Delta V_Q$  and  $\Delta V_{ESR}$ . Assume that input-voltage ripple from the ESR and the capacitor discharge is equal to 50% each. The following equations show the ESR and capacitor requirement for a target voltage ripple at the input:

**Equation 3:** 

$$ESR = \frac{\Delta V_{ESR}}{I_{OUT} + (\Delta I_{P-P} / 2)}$$
$$C_{IN} = \frac{I_{OUT} \times D(1 - D)}{\Delta V_{Q} \times f_{SW}}$$

where:

$$\Delta I_{P-P} = \frac{(V_{IN} - V_{OUT}) \times V_{OUT}}{V_{IN} \times f_{SW} \times L}$$

and:

$$D = \frac{V_{OUT}}{V_{IN}}$$

where  $I_{OUT}$  is the output current, D is the duty cycle, and  $f_{SW}$  is the switching frequency. Use additional input capacitance at lower input voltages to avoid possible undershoot below the UVLO threshold during transient loading.

### **Output Capacitor**

The output ripple comprises  $\Delta V_Q$  (caused by the capacitor discharge) and  $\Delta V_{ESR}$  (caused by the ESR of the output capacitor). Use low-ESR ceramic or aluminum electrolytic capacitors at the output. For aluminum electrolytic capacitors, the entire output ripple is contributed by  $\Delta V_{ESR}$ . The output filter capacitor must have enough capacitance and sufficiently low ESR to meet output-ripple requirements. To satisfy the specified output-voltage ripple, the output capacitance is calculated as follows:

$$C_{OUT(MIN1)} = \frac{I_{OUT} \times LIR}{8 \times f_{SW} \times (\Delta V_Q - ESR \times I_{OUT} \times LIR)}$$

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When using low-ESR (e.g. ceramic) output capacitors, size is usually determined by the capacitance required to maintain the output voltage within specification during load transients and can be estimated as follows:

$$C_{OUT(MIN2)} = \frac{V_{REF} \times G_m \times R_{COMP}}{2 \times \pi \times V_{OUT} \times R_i \times f_C}$$

Here  $V_{REF}$  is the reference of the feedback voltage with the value of 0.8V,  $G_m$  is the gain of the transconductance error amplifier with thve value of 60µA/V (typ),  $R_{COMP}$  is the compensation network resistor with the value of 185k $\Omega$ .  $R_i$  is current-sense gain of 0.5 (typ).  $f_C$  is the desired loop crossover frequency, which usually is selected between of  $f_{SW}/20$  and  $f_{SW}/10$ .

Select the larger of  $C_{OUT(MIN1)}$  and  $C_{OUT(MIN2)}$  as the output capacitor.

$$C_{OUT} = max(C_{OUT(MIN1)}, C_{OUT(MIN2)})$$

Any calculations involving  $C_{OUT}$  should consider capacitance tolerance, temperature, and voltage derating. For ceramic output capacitors, the actual capacitance is properly derated according to the applied DC voltage. For more accurate derating models, refer to the manufacturer data sheets for the output capacitors being used.

### **Soft-Start Capacitor Selection**

The IC implements adjustable soft-start operation to reduce inrush current. A capacitor connected from the SS pin to SGND programs the soft-start time for the corresponding output voltage. The selected output capacitance (C<sub>SEL</sub>) and the output voltage (V<sub>OUT</sub>) determine the minimum required soft-start capacitor as shown below:

### Equation 6:

$$C_{SS} \ge 30 \times 10^{-6} \times C_{SEL} \times V_{OUT}$$

The soft-start time  $(t_{SS})$  is related to the capacitor connected at SS  $(C_{SS})$  by the following equation:

### Equation 7:

$$t_{SS} = \frac{C_{SS}}{6.25 \times 10^{-6}}$$

For example, to program a 2ms soft-start time, connect a 12nF capacitor from the SS pin to SGND.

### Adjusting the Output Voltage

Set the output voltage with resistive voltage-dividers connected from the positive terminal of the output capacitor (V<sub>OUT</sub>) to SGND (Figure 1). Connect the center node of the divider to the FB pin. To optimize efficiency and output accuracy, use the following calculations to choose the resistive divider values:

### **Equation 8:**

$$R4 = \frac{15 \times V_{OUT}}{0.8}$$
$$R5 = \frac{R4 \times 0.8}{(V_{OUT} - 0.8)}$$

where R4 and R5 are in  $k\Omega$ .

### **Feed-Forward Cap Selection**

To increase the phase margin and bandwidth,  $C_6$  is paralleled with the top resistor  $R_4$  of the feedback resistance divider to provide a zero around the desired crossover frequency ( $f_C$ ). It is convenient to put  $R_4$  to a fixed value and vary  $R_5$  to set the output voltage  $V_{OUT}$ .

$$C_6 = \frac{1}{2 \times \pi \times R_4 \times f_c}$$

### Setting the Undervoltage Lockout

Drive EN/UVLO high to enable the output. Leave the pin unconnected for always-on operation. Set the voltage at which each converter turns on with a resistive voltage-divider connected from V<sub>IN</sub> to SGND (Figure 3). Connect the center node of the divider to EN/UVLO pin.

### Equation 10 (choose R1 as follows):

where  $V_{INU}$  is the input voltage at which the device is required to turn on and R1 is in  $\Omega$ . Calculate the value of R2 as shown in Equation 11.

### Equation 11:

$$R2 = \frac{1.215 \times R1}{(V_{INU} - 1.215 + (2.5 \mu A \times R1))}$$

## 72V, 1A, Automotive Synchronous Step-Down DC-DC Converter



Figure 1. Setting the Output Voltage



Figure 2. R-C Network for Increased Phase Margin



Figure 3. Undervoltage-Lockout Divider

### **PCB Layout Guidelines**

Careful PCB layout is critical to achieve low switching power losses and clean, stable operation. Use a multilayer board wherever possible for better noise immunity. Follow the guidelines below for a good PCB layout:

- Place the input capacitor next to the V<sub>IN</sub> pin. The bypass capacitor for the V<sub>CC</sub> pin should be as close as possible to the pin. The feedback trace should be routed away from the inductor.
- 2) Solder the exposed pad to a large copper-plane area under the device. To effectively use this copper area as a heat exchanger between the PCB and ambient, expose the copper area on the top and bottom side. Add a few small vias or one large via on the copper pad for efficient heat transfer. Connect the exposed pad to PGND, ideally at the return terminal of the output capacitor.

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- 3) Isolate the power components and high-current paths from sensitive analog circuitry.
- 4) Keep the high-current paths short, especially at the ground terminals. This practice is essential for stable, jitter-free operation.
- 5) Connect PGND and SGND together, preferably at the return terminal of the input capacitor. Do not connect them anywhere else.
- Keep the power traces and load connections short. This practice is essential for high efficiency. Use thick copper PCB to enhance full-load efficiency and power-dissipation capability.
- Route high-speed switching nodes away from sensitive analog areas. Use internal PCB layers as PGND to act as EMI shields to keep radiated noise away from the device and analog bypass capacitor.



### **Typical Application Circuit**

## **Chip Information**

PROCESS: CMOS

### **Ordering Information**

PART	TEMP RANGE	PIN-PACKAGE
MAX20059ATCA/VY+	-40°C to +125°C	12 SW TDFN-EP*

/V Denotes an automotive-qualified part.

+Denotes a lead(Pb)-free/RoHS-compliant package.

SW = Side-wettable package.

\*EP = Exposed pad.

## 72V, 1A, Automotive Synchronous Step-Down DC-DC Converter

## **Revision History**

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	7/18	Initial release	_
1	6/19	Updated Absolute Maximum Ratings and Applications Information	2, 14, 15
2	2/20	Updated <i>Inductor Selection</i> section, <i>Output Capacitor</i> section added <i>Feed-forward cap selection</i> section, updated <i>Figure 2</i> and <i>Typical Application Circuit</i> figure	13, 15, 16

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