## Dual, 10-Bit, 165Msps, Current-Output DAC

#### **General Description**

The MAX5854 dual, 10-bit, 165Msps digital-to-analog converter (DAC) provides superior dynamic performance in wideband communication systems. The device integrates two 10-bit DAC cores, and a 1.24V reference. The MAX5854 supports single-ended and differential modes of operation. The dynamic performance is maintained over the entire 2.7V to 3.6V power-supply operating range. The analog outputs support a -1.0V to +1.25V compliance voltage.

The MAX5854 can operate in interleaved data mode to reduce the I/O pin count. This allows the converter to be updated on a single, 10-bit bus.

The MAX5854 features digital control of channel gain matching to within  $\pm 0.4 dB$  in sixteen 0.05dB steps. Channel matching improves sideband suppression in analog quadrature modulation applications. The on-chip 1.24V bandgap reference includes a control amplifier that allows external full-scale adjustments of both channels through a single resistor. The internal reference can be disabled and an external reference can be applied for high-accuracy applications.

The MAX5854 features full-scale current outputs of 2mA to 20mA and operates from a 2.7V to 3.6V single supply. The DAC supports three modes of power-control operation: normal, low-power standby, and complete power-down. In power-down mode, the operating current is reduced to  $1\mu A.$ 

The MAX5854 is packaged in a 40-pin TQFN with exposed paddle (EP) and is specified for the extended (-40°C to +85°C) temperature range.

Pin-compatible, lower speed, and lower resolution versions are also available. Refer to the MAX5853 (10-bit, 80Msps), the MAX5852 (8-bit, 165Msps), and the MAX5851 (8-bit, 80Msps) data sheets for more information. See Table 4 at the end of the data sheet.

## **Applications**

- Communications
  - SatCom, LMDS, MMDS, HFC, DSL, WLAN, Point-to-Point Microwave Links
- Wireless Base Stations
- Quadrature Modulation
- Direct Digital Synthesis (DDS)
- Instrumentation/ATE

#### **Features**

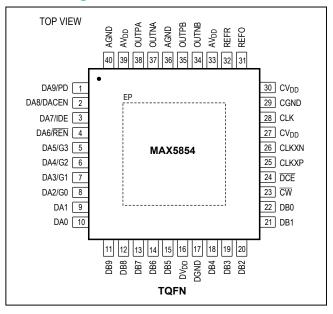
- 10-Bit, 165Msps Dual DAC
- Low Power
- 190mW with  $I_{FS}$  = 20mA at  $f_{CLK}$  = 165MHz
- 2.7V to 3.6V Single Supply
- Full Output Swing and Dynamic Performance at 2.7V Supply
- Superior Dynamic Performance
  - 73dBc SFDR at fOUT = 40MHz
  - UMTS ACLR = 65.5dB at f<sub>OUT</sub> = 30.7MHz
- Programmable Channel Gain Matching
- Integrated 1.24V Low-Noise Bandgap Reference
- Single-Resistor Gain Control
- Interleaved Data Mode
- Single-Ended and Differential Clock Input Modes
- Miniature 40-Pin TQFN Package, 6mm x 6mm
- EV Kit Available—MAX5854 EV Kit

## **Ordering Information**

PART	TEMP RANGE	PIN-PACKAGE
MAX5854ETL	-40°C to +85°C	40 Thin QFN-EP*

\*EP = Exposed paddle.

## **Pin Configuration**





## **Absolute Maximum Ratings**

AV <sub>DD</sub> , DV <sub>DD</sub> , CV <sub>DD</sub> to AGND, DGND	), CGND0.3V to +4V
DA9-DA0, DB9-DB0, CW, DCE to A	GND,
DGND, CGND	0.3V to +4V
CLKXN, CLKXP to CGND	0.3V to +4V
OUTP_, OUTN_ to AGND	1.25V to (AV <sub>DD</sub> + 0.3V)
CLK to DGND	0.3V to $(DV_{DD}^{-} + 0.3V)$
REFR, REFO to AGND	0.3V to $(AV_{DD} + 0.3V)$

AGND to DGND, DGND to CGND,	
AGND to CGND	0.3V to +0.3V
Maximum Current into Any Pin	
(excluding power supplies)	±50mA
Continuous Power Dissipation ( $T_A = +70$ °C)	
40-Pin TQFN-EP (derate 23.3mW/°C	
above +70°C)	
Operating Temperature Range	-40°C to +85°C
Storage Temperature Range	65°C to +150°C
Junction Temperature	+150°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### **Electrical Characteristics**

 $(AV_{DD} = DV_{DD} = CV_{DD} = 3V, AGND = DGND = CGND = 0, f_{DAC} = 165Msps, differential clock, external reference, <math>V_{REF} = 1.2V, I_{FS} = 20mA$ , output amplitude = 0dB FS, differential output,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted.  $T_A \ge +25^{\circ}C$  guaranteed by production test.  $T_A < +25^{\circ}C$  guaranteed by design and characterization. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS	
STATIC PERFORMANCE				•				
Resolution	N			10			Bits	
Integral Nonlinearity	INL	R <sub>L</sub> = 0		-1.0	±0.25	+1.0	LSB	
Differential Nonlinearity	DNL	Guaranteed monotor	nic, R <sub>L</sub> = 0	-0.5	±0.2	+0.5	LSB	
Offset Error	Vos			-0.5	±0.1	+0.5	LSB	
Gain Error (See Also Gain Error	GE	Internal reference (N	lote1)	-11.0	±1.5	+6.8	%FSR	
Definition Section)	GE	External reference		-6.25	±0.7	+4.10	%F3R	
Cain Francisco Drift		Internal reference			±150		"0.0	
Gain-Error Temperature Drift		External reference		±100		ppm/°C		
DYNAMIC PERFORMANCE				•				
	SFDR	f <sub>CLK</sub> = 165MHz, A <sub>OUT</sub> = -1dBFS	f <sub>OUT</sub> = 10MHz	69.4	78			
			f <sub>OUT</sub> = 20MHz		77			
			f <sub>OUT</sub> = 40MHz		73		1	
Spurious-Free Dynamic Range		f <sub>CLK</sub> = 100MHz, A <sub>OUT</sub> = -1dBFS	f <sub>OUT</sub> = 10MHz	77			dBc	
to Nyquist			f <sub>OUT</sub> = 20MHz	77 76		UDC		
			f <sub>OUT</sub> = 30MHz					
		f <sub>CLK</sub> = 25MHz, A <sub>OUT</sub> = -1dBFS	f <sub>OUT</sub> = 1MHz	79				
		f <sub>CLK</sub> = 165MHz, f <sub>OUT</sub> = 10MHz, A <sub>OUT</sub> = -1dBFS, span = 10MHz			83			
Spurious-Free Dynamic Range Within a Window	SFDR		f <sub>CLK</sub> = 100MHz, f <sub>OUT</sub> = 5MHz, A <sub>OUT</sub> = -1dBFS, span = 4MHz		84		dBc	
		f <sub>CLK</sub> = 25MHz, f <sub>OUT</sub> = 1MHz, A <sub>OUT</sub> = -1dBFS, span = 2MHz			82			
Multitone Power Ratio to Nyquist	MTPR	8 tones at 400kHz sp f <sub>OUT</sub> = 15MHz to 18.	pacing, f <sub>CLK</sub> = 78MHz, .2MHz		74		dBc	

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PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
Multitone Spurious-Free Dynamic Range Within a Window		8 tones at 2.1MHz sp f <sub>CLK</sub> = 165MHz, f <sub>OUT</sub> span = 50MHz	pacing, r = 28.3MHz to 45.2MHz,		70		dBc
Adjacent Channel Power Ratio with UMTS	ACLR	f <sub>OUT</sub> = 30.72MHz, RI f <sub>CLK</sub> = 122.88MHz	BW = 30kHz,		65.5		dB
			f <sub>OUT</sub> = 10MHz		-76		
		f <sub>CLK</sub> = 165MHz, A <sub>OUT</sub> = -1dBFS	f <sub>OUT</sub> = 20MHz		-74		
		A001 = -10B1 3	f <sub>OUT</sub> = 40MHz		-71		
Total Harmonic Distortion to	THD		f <sub>OUT</sub> = 10MHz		-75		dDo
Nyquist (2nd- Through 8th-Order Harmonics Included)	טחו	f <sub>CLK</sub> = 100MHz, A <sub>OUT</sub> = -1dBFS	f <sub>OUT</sub> = 20MHz		-74		dBc
,		AOUT IUBES	f <sub>OUT</sub> = 30MHz		-73	,	
		f <sub>CLK</sub> = 25MHz, A <sub>OUT</sub> = -1dBFS	f <sub>OUT</sub> = 1MHz		-76		
Output Channel-to-Channel Isolation		f <sub>OUT</sub> = 10MHz			90		dB
Channel-to-Channel Gain Mismatch		f <sub>OUT</sub> = 10MHz, G[3:0] = 1000		0.025			dB
Channel-to-Channel Phase Mismatch		f <sub>OUT</sub> = 10MHz			0.05		Degrees
		f <sub>CLK</sub> = 165MHz, f <sub>OUT</sub> = 10MHz, I <sub>FS</sub> = 20mA			60.5		
Cignal to Naise Datio to Naguist	SNR	f <sub>CLK</sub> = 165MHz, f <sub>OUT</sub> = 10MHz, I <sub>FS</sub> = 5mA			61		40
Signal-to-Noise Ratio to Nyquist		f <sub>CLK</sub> = 65MHz, f <sub>OUT</sub> = 10MHz, I <sub>FS</sub> = 20mA			62		dB
		f <sub>CLK</sub> = 65MHz, f <sub>OUT</sub> = 10MHz, I <sub>FS</sub> = 5mA			62		
Maximum DAC Conversion Data	f <sub>DAC</sub>	Interleaved mode disabled, IDE = 0		165	200		Mono
Maximum DAC Conversion Rate		Interleaved mode enabled, IDE = 1		82.5	100		Msps
Glitch Impulse					5		pV-s
Output Settling Time	t <sub>S</sub>	To ±0.1% error band	(Note 3)		12		ns
Output Rise Time		10% to 90% (Note 3)			2.2		ns
Output Fall Time		90% to 10% (Note 3)			2.2		ns
ANALOG OUTPUT							
Full-Scale Output Current Range	I <sub>FS</sub>			2		20	mA
Output Voltage Compliance Range				-1.00		+1.25	V
Output Leakage Current		Shutdown or standby mode		-5		+5	μA
REFERENCE							
Internal-Reference Output Voltage	V <sub>REFO</sub>	REN = 0		1.13	1.24	1.32	V

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PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Internal-Reference Supply Rejection		AV <sub>DD</sub> varied from 2.7V to 3.6V		0.5		mV/V
Internal-Reference Output- Voltage Temperature Drift	TCV <sub>REFO</sub>	REN = 0		±50		ppm/°C
Internal-Reference Output Drive Capability		REN = 0		50		μA
External-Reference Input Voltage Range		REN = 1	0.10	1.2	1.32	V
Current Gain	I <sub>FS</sub> /I <sub>REF</sub>			32		mA/mA
LOGIC INPUTS (DA9-DA0, DB9	–DB0, <del>CW</del> )					
Digital Input-Voltage High	V <sub>IH</sub>		0.65 x DV <sub>DD</sub>			V
Digital Input-Voltage Low	V <sub>IL</sub>				$^{0.3}$ x $^{DV}$	V
Digital Input Current	I <sub>IN</sub>		-1		+1	μA
Digital Input Capacitance	C <sub>IN</sub>			3		pF
SINGLE-ENDED CLOCK INPUT	OUTPUT AI	ND $\overline{\text{DCE}}$ INPUT (CLK, $\overline{\text{DCE}}$ )				
Digital Input-Voltage High	V <sub>IH</sub>	DCE = 1	0.65 x CV <sub>DD</sub>			V
Digital Input-Voltage Low	V <sub>IL</sub>	DCE = 1			0.3 x CV <sub>DD</sub>	V
Digital Input Current	I <sub>IN</sub>	DCE = 1	-1		+1	μA
Digital Input Capacitance	C <sub>IN</sub>	DCE = 1		3		pF
Digital Output-Voltage High	V <sub>OH</sub>	DCE = 0, I <sub>SOURCE</sub> = 0.5mA, Figure 1	0.9 x CV <sub>DD</sub>			V
Digital Output-Voltage Low	V <sub>OL</sub>	DCE = 0, I <sub>SINK</sub> = 0.5mA, Figure 1			0.1 x CV <sub>DD</sub>	V
DIFFERENTIAL CLOCK INPUTS	CLKXP/CI	KXN)				
Differential Clock Input Internal Bias				CV <sub>DD</sub> /2		V
Differential Clock Input Swing			0.5			V
Clock Input Impedance		Measured single ended		5		kΩ
POWER REQUIREMENTS			,			
Analog Power-Supply Voltage	AV <sub>DD</sub>		2.7	3	3.6	V
Digital Power-Supply Voltage	DV <sub>DD</sub>		2.7	3	3.6	V
Clock Power-Supply Voltage	CV <sub>DD</sub>		2.7	3	3.6	V

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PARAMETER	SYMBOL	COND	ITIONS	MIN	TYP	MAX	UNITS
		I <sub>FS</sub> = 20mA (Note 2), single-ended clock mode			43.2	46	
		I <sub>FS</sub> = 20mA (Note 2), d	ifferential clock mode		43.2		
Analog Supply Current	IAVDD	I <sub>FS</sub> = 2mA (Note 2), sin	gle-ended clock mode		5	mA	
		I <sub>FS</sub> = 2mA (Note 2), diff	ferential clock mode		5		
District Constant		I <sub>FS</sub> = 20mA (Note 2), si	ingle-ended clock mode		6.2	7.5	
Digital Supply Current	IDVDD	I <sub>FS</sub> = 20mA (Note 2), d	ifferential clock mode		6.2		mA
Olari Orani Orani		Single-ended clock mo	de (DCE = 1) (Note 2)		13.7	16.5	
Clock Supply Current	ICVDD	Differential clock mode	(DCE = 0) (Note 2)		24		mA
Total Standby Current	ISTANDBY	I <sub>AVDD</sub> + I <sub>DVDD</sub> + I <sub>CVDD</sub>			3.1	3.7	mA
Total Shutdown Current	I <sub>SHDN</sub>	I <sub>AVDD</sub> + I <sub>DVDD</sub> + I <sub>CVDE</sub>	)		1		μA
		Single-ended clock	I <sub>FS</sub> = 20mA (Note 2)		190	210	
		mode (DCE = 1)	I <sub>FS</sub> = 2mA (Note 2)		75		mW
	P <sub>TOT</sub>	Differential clock mode	I <sub>FS</sub> = 20mA (Note 2)		220		
Total Power Dissipation		(DCE = 0)	I <sub>FS</sub> = 2mA (Note 2)		106		
		Standby		9.3			
		Shutdown		0.003			
TIMING CHARACTERISTICS (Fi	gure 5, Figu	ire 6)					
Propagation Delay					1		Clock cycles
DAC Data to CLK Rise/Fall		Single-ended clock mode (DCE = 1) (Note 4)					
Setup Time	t <sub>DCS</sub>	Differential clock mode (DCE = 0) (Note 4)					ns
DAC Data to CLK Rise/Fall Hold		Single-ended clock mode (DCE = 1) (Note 4)		0.8			
Time	t <sub>DCH</sub>	Differential clock mode (DCE = 0) (Note 4)					ns
Control Word to CW Rise Setup Time	t <sub>CS</sub>			2.5			ns
Control Word to $\overline{\text{CW}}$ Rise Hold Time	t <sub>CW</sub>			2.5			ns
CW High Time	tcwH			5			ns
CW Low Time	t <sub>CWL</sub>			5			ns
DACEN = 1 to V <sub>OUT</sub> Stable Time (Coming Out of Standby)	t <sub>STB</sub>				3		μs

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PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
PD = 0 to V <sub>OUT</sub> Stable Time (Coming Out of Power-Down)	t <sub>SHDN</sub>			500		μs
Maximum Clock Frequency at CLKXP/CLKXN Input	f <sub>CLK</sub>		165	200		MHz
Clock High Time	t <sub>CXH</sub>	CLKXP or CLKXN input		1.5		ns
Clock Low Time	t <sub>CXL</sub>	CLKXP or CLKXN input		1.5		ns
CLKXP Rise to CLK Output Rise Delay	t <sub>CDH</sub>	DCE = 0		2.7		ns
CLKXP Fall to CLK Output Fall Delay	t <sub>CDL</sub>	DCE = 0		2.7		ns

Note 1: Including the internal reference voltage tolerance and reference amplifier offset.

**Note 2:**  $f_{DAC} = 165Msps$ ,  $f_{OUT} = 10MHz$ .

Note 3: Measured single-ended with  $50\Omega$  load and complementary output connected to AGND.

Note 4: Guaranteed by design, not production tested.

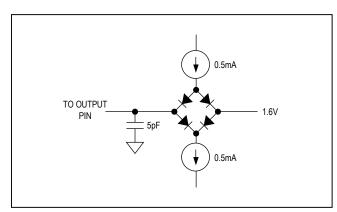
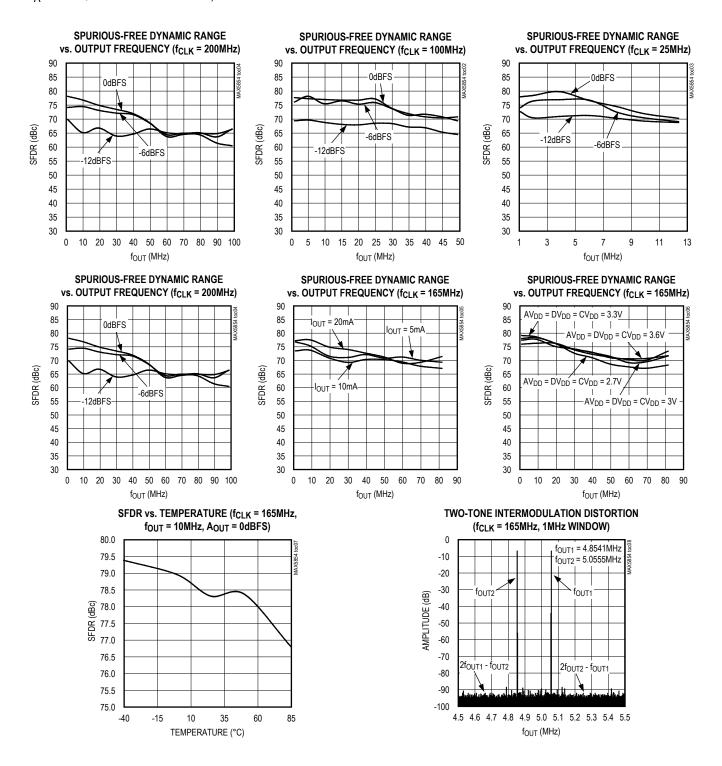


Figure 1. Load Test Circuit for CLK Outputs

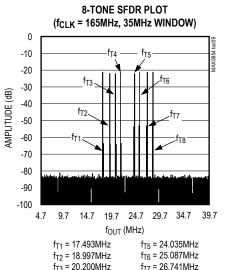
## **Typical Operating Characteristics**

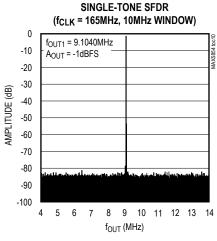
 $(AV_{DD} = DV_{DD} = CV_{DD} = 3V, AGND = DGND = CGND = 0,$  external reference, differential clock,  $I_{FS} = 20$ mA, differential output,  $T_A = +25$ °C, unless otherwise noted.)

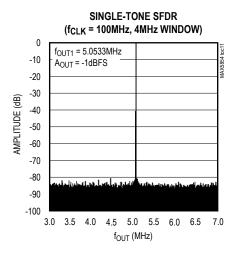


## **Typical Operating Characteristics (continued)**

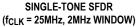
 $(AV_{DD} = DV_{DD} = CV_{DD} = 3V, AGND = DGND = CGND = 0, external reference, differential clock, I<sub>FS</sub> = 20mA, differential output,$  $T_A = +25$ °C, unless otherwise noted.)

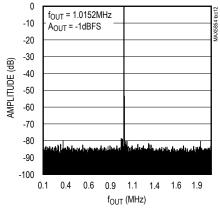


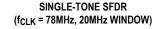


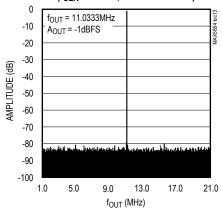


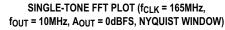


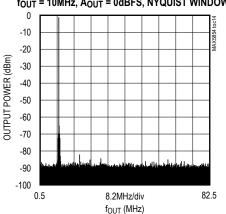


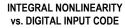


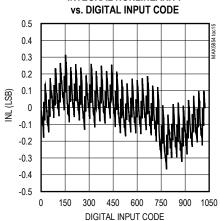






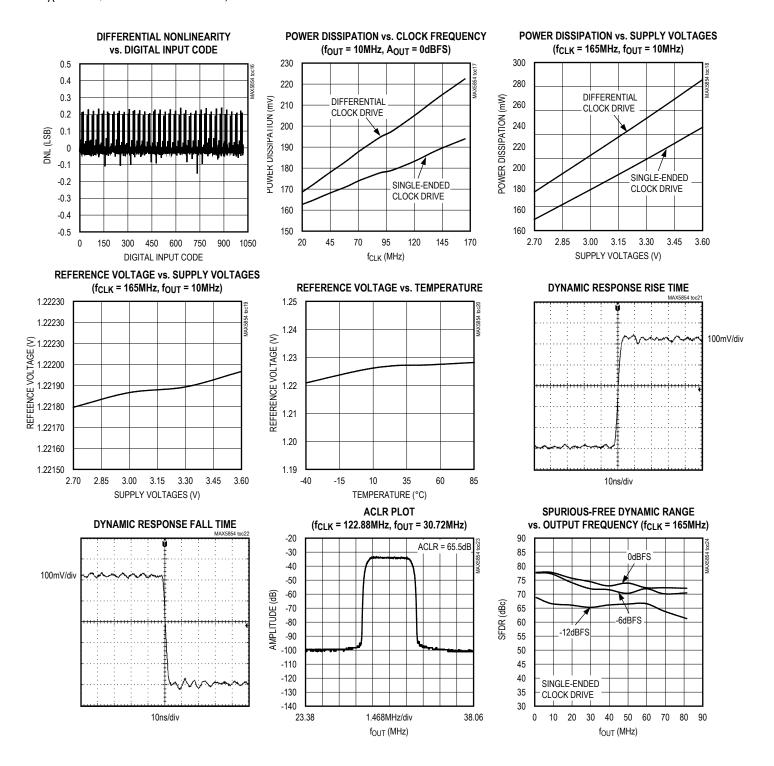






## **Typical Operating Characteristics (continued)**

 $(AV_{DD} = DV_{DD} = CV_{DD} = 3V, AGND = DGND = CGND = 0,$  external reference, differential clock,  $I_{FS} = 20$ mA, differential output,  $T_A = +25$ °C, unless otherwise noted.)



## **Pin Description**

PIN	NAME	FUNCTION
1	DA9/PD	Channel A Input Data Bit 9 (MSB)/Power-Down
2	DA8/DACEN	Channel A Input Data Bit 8/DAC Enable Control
3	DA7/IDE	Channel A Input Data Bit 7/Interleaved Data Enable
4	DA6/REN	Channel A Input Data Bit 6/Reference Enable. Setting REN = 0 enables the internal reference. Setting REN = 1 disables the internal reference.
5	DA5/G3	Channel A Input Data Bit 5/Channel A Gain Adjustment Bit 3
6	DA4/G2	Channel A Input Data Bit 4/Channel A Gain Adjustment Bit 2
7	DA3/G1	Channel A Input Data Bit 3/Channel A Gain Adjustment Bit 1
8	DA2/G0	Channel A Input Data Bit 2/Channel A Gain Adjustment Bit 0
9	DA1	Channel A Input Data Bit 1
10	DA0	Channel A Input Data Bit 0 (LSB)
11	DB9	Channel B Input Data Bit 9 (MSB)
12	DB8	Channel B Input Data Bit 8
13	DB7	Channel B Input Data Bit 7
14	DB6	Channel B Input Data Bit 6
15	DB5	Channel B Input Data Bit 5
16	DV <sub>DD</sub>	Digital Power Input. See the Power Supplies, Bypassing, Decoupling, and Layout section for more details.
17	DGND	Digital Ground
18	DB4	Channel B Input Data Bit 4
19	DB3	Channel B Input Data Bit 3
20	DB2	Channel B Input Data Bit 2
21	DB1	Channel B Input Data Bit 1
22	DB0	Channel B Input Data Bit 0 (LSB)
23	CW	Active-Low Control Word Write Pulse. The control word is latched on the rising edge of $\overline{\text{CW}}$ .
24	DCE	Active-Low Differential Clock Enable Input. Drive DCE low to enable the differential clock inputs CLKXP and CLKXN. Drive DCE high to disable the differential clock inputs and enable the single-ended CLK input.
25	CLKXP	Positive Differential Clock Input. With $\overline{DCE} = 0$ , CLKXP and CLKXN are enabled. With $\overline{DCE} = 1$ , CLKXP and CLKXN are disabled. Connect CLKXP to CGND when the differential clock is disabled.
26	CLKXN	Negative Differential Clock Input. With $\overline{DCE}$ = 0, CLKXP and CLKXN are enabled. With $\overline{DCE}$ = 1, CLKXP and CLKXN are disabled. Connect CLKXN to CV <sub>DD</sub> when the differential clock is disabled.
27, 30	CV <sub>DD</sub>	Clock Power Input. See the <i>Power Supplies, Bypassing, Decoupling, and Layout</i> section for more details.
28	CLK	Single-Ended Clock Input/Output. With the differential clock disabled ( $\overline{DCE}$ = 1), CLK becomes a single-ended conversion clock input. With the differential clock enabled ( $\overline{DCE}$ = 0), CLK is a single-ended output that mirrors the differential clock inputs CLKXP and CLKXN. See the <i>Clock Modes</i> section for more information on CLK.
29	CGND	Clock Ground
31	REFO	Reference Input/Output. REFO serves as a reference input when the internal reference is disabled. If the internal 1.24V reference is enabled, REFO serves as an output for the internal reference. When the internal reference is enabled, bypass REFO to AGND with a 0.1µF capacitor

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PIN	NAME	FUNCTION
32	REFR	Full-Scale Current Adjustment. To set the output full-scale current, connect an external resistor RSET between REFR and AGND. The output full-scale current is equal to 32 x V <sub>REFO</sub> /R <sub>SET</sub> .
33, 39	AV <sub>DD</sub>	Analog Power Input. See the Power Supplies, Bypassing, Decoupling, and Layout section for more details.
34	OUTNB	Channel B Negative Analog Current Output
35	OUTPB	Channel B Positive Analog Current Output
36, 40	AGND	Analog Ground
37	OUTNA	Channel A Negative Analog Current Output
38	OUTPA	Channel A Positive Analog Current Output
_	FP	Exposed Paddle Connect EP to the common point of all ground planes

## **Pin Description (continued)**

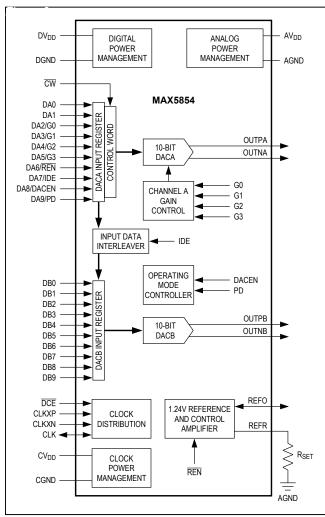


Figure 2. Simplified Diagram

## **Detailed Description**

The MAX5854 dual, high-speed, 10-bit, current-output DAC provides superior performance in communication systems requiring low-distortion analog-signal reconstruction. The MAX5854 combines two DACs and an on-chip 1.24V reference (Figure 2). The current outputs of the DACs can be configured for differential or single-ended operation. The full-scale output current range is adjustable from 2mA to 20mA to optimize power dissipation and gain control.

The MAX5854 accepts an input data and a DAC conversion rate of 165MHz. The inputs are latched on the rising edge of the clock whereas the output latches on the following rising edge.

The MAX5854 features three modes of operation: normal, standby, and power-down (Table 2). These modes allow efficient power management. In power-down, the MAX5854 consumes only 1µA of supply current. Wake-up time from standby mode to normal DAC operation is 3µs.

#### Programming the DAC

An 8-bit control word routed through channel A's data port programs the gain matching, reference, and the operational mode of the MAX5854. The control word is latched on the rising edge of  $\overline{\text{CW}}$ .  $\overline{\text{CW}}$  is independent of the DAC clock. The DAC clock can always remain running, when the control word is written to the DAC. Table 1 and Table 2 represent the control word format and function.

The gain on channel A can be adjusted to achieve gain matching between two channels in a user's system. The gain on channel A can be adjusted from -0.4dB to 0.35dB in steps of 0.05dB by using bits G3 to G0 (Table 3).

**Table 1. Control Word Format and Function** 

MSB									LSB
PD	DACEN	IDE	REN	G3	G2	G1	G0	Х	Х
CONTROI	L WORD				FUNCT	ION			
PE	)	Power-Down. Th	ne part enters	power-down	mode if PD =	1.			
DAC	EN	DAC Enable. Wh	nen DACEN =	0 and PD = 0	), the part ent	ers standby m	node.		
IDI	E	Interleaved Data is applied throug signal and chann	h channel A i	n a multiplexe	d fashion. Ch	annel B data i	is written on th	•	
RE	N	Reference Enable Bit. $\overline{REN}$ = 0 activates the internal reference. $\overline{REN}$ = 1 disables the internal reference and requires the user to apply an external reference between 0.1V to 1.32V.							
G	3	Bit 3 (MSB) of G	ain Adjust Wo	ord					
G2	2	Bit 2 of Gain Adjust Word							
G′	1	Bit 1 of Gain Adjust Word							
G	G0 Bit 0 (LSB) of Gain Adjust Word								

**Table 2. Configuration Modes** 

MODE	PD	DACEN	IDE	REN
Normal operation; noninterleaved inputs; internal reference active	0	1	0	0
Normal operation; noninterleaved inputs; internal reference disabled	0	1	0	1
Normal operation; interleaved inputs; internal reference disabled	0	1	1	1
Standby	0	0	Х	Х
Power-down	1	Х	Х	Х
Power-up	0	1	Х	Х

X = Don't care.

**Table 3. Gain Difference Setting** 

GAIN ADJUSTMENT ON CHANNEL A (dB)	G3	G2	G1	G0
+0.4	0	0	0	0
0	1	0	0	0
-0.35	1	1	1	1

## **Device Power-Up and States of Operation**

At power-up, the MAX5854's default configuration is internal reference noninterleaved input mode with a gain of 0dB and a fully operational converter. In shutdown, the MAX5854 consumes only  $1\mu A$  of supply current, and in standby the current consumption is 3.1mA. Wake-up time from standby mode to normal operation is  $3\mu s$ .

#### **Clock Modes**

The MAX5854 allows both single-ended CMOS and differential clock mode operation, and supports update rates of up to 165Msps. These modes are selected through an active-low control line called  $\overline{DCE}$ . In single-ended clock mode ( $\overline{DCE}$  = 1), the CLK pin functions as an input, which accepts a user-provided single-ended clock signal. Data is written to the converter on the rising edge of the clock. The DAC outputs (previous data) are updated simultaneously on the same edge.

If the  $\overline{DCE}$  pin is pulled low, the MAX5854 will operate in differential clock mode. In this mode, the clock signal has to be applied to differential clock input pins CLKXP/CLKXN. The differential input accepts an input range of  $\geq 0.5 V_{P-P}$  and a common-mode range of 1V to (CV<sub>DD</sub> - 0.5V), making the part ideal for low-input amplitude clock drives. CLKXP/CLKXN also help to minimize the jitter, and allow the user to connect a crystal oscillator directly to MAX5854.

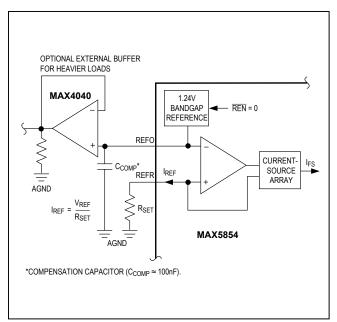


Figure 3. Setting  $I_{FS}$  with the Internal 1.24V Reference and the Control Amplifier

The CLK pin now becomes an output, and provides a single-ended replica of the differential clock signal, which can be used to synchronize the input data. Data is written to the device on the rising edge of the CLK signal.

#### Internal Reference and Control Amplifier

The MAX5854 provides an integrated 50ppm/°C, 1.24V, low-noise bandgap reference that can be disabled and overridden with an external reference voltage. REFO serves either as an external reference input or an integrated reference output. If  $\overline{\text{REN}} = 0$ , the internal reference is selected and REFO provides a 1.24V (50µA) output. Buffer REFO with an external amplifier, when driving a heavy load.

The MAX5854 also employs a control amplifier designed to simultaneously regulate the full-scale output current ( $I_{FS}$ ) for both outputs of the devices. Calculate the output current as:

$$I_{FS} = 32 \times I_{REF}$$

where I<sub>REF</sub> is the reference output current (I<sub>REF</sub> = V<sub>REFO</sub>/ R<sub>SET</sub>) and I<sub>FS</sub> is the full-scale output current. R<sub>SET</sub> is the reference resistor that determines the amplifier output current of the MAX5854 (<u>Figure 3</u>). This current is mirrored into the current-source array where I<sub>FS</sub> is equally distributed between matched current segments and summed to valid output current readings for the DACs.

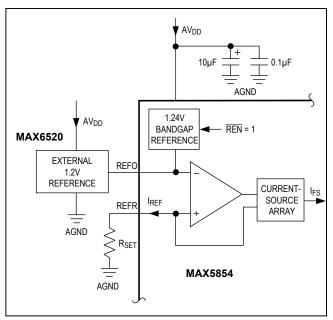


Figure 4. MAX5854 with External Reference

#### **External Reference**

To disable the internal reference of the MAX5854, set REN = 1. Apply a temperature-stable, external reference to drive the REFO pin and set the full-scale output (Figure 4). For improved accuracy and drift performance, choose a fixed output voltage reference such as the 1.2V, 25ppm/°C MAX6520 bandgap reference.

#### **Detailed Timing**

The MAX5854 accepts an input data and the DAC conversion rate of up to 165Msps. The input latches on the rising edge of the clock, whereas the output latches on the following rising edge.

<u>Figure 5</u> depicts the write cycle of the two DACs in non-interleaved mode.

The MAX5854 can also operate in an interleaved data mode. Programming the IDE bit with a high level activates this mode (Table 1 and Table 2). In interleaved mode, data for both DAC channels is written through input port A. Channel B data is written on the falling edge of the clock signal and then channel A data is written on the following rising edge of the clock signal. Both DAC outputs (channel A and B) are updated simultaneously on the next following rising edge of the clock. In interleaved data mode, the maximum input data rate per channel is half of the rate in noninterleaved mode. The interleaved data mode is attractive for applications where lower data rates are acceptable and interfacing on a single 10-bit bus is desired (Figure 6).

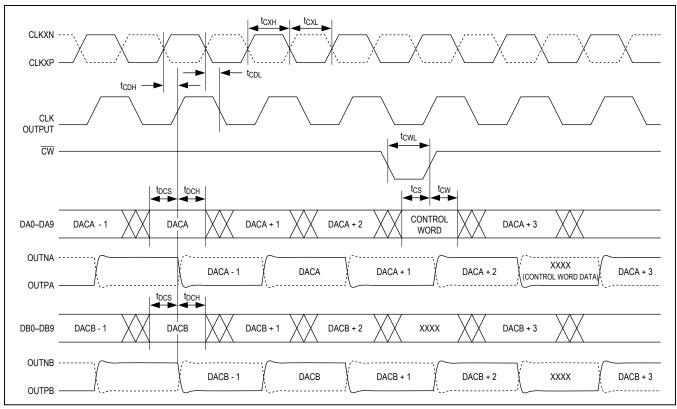


Figure 5. Timing Diagram for Noninterleaved Data Mode (IDE = 0)

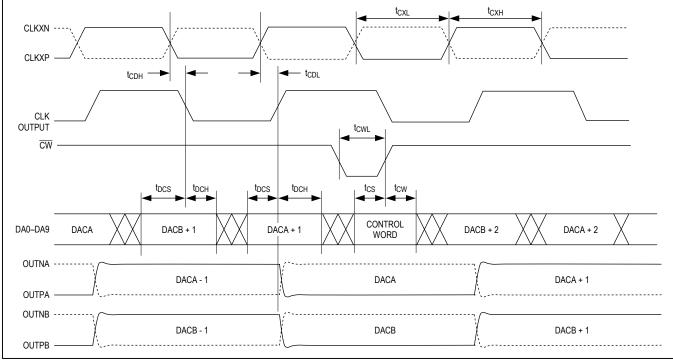


Figure 6. Timing Diagram for Interleaved Data Mode (IDE = 1)

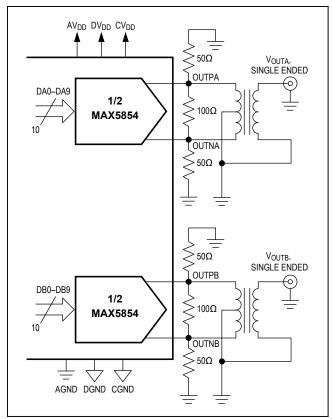


Figure 7. Application with Output Transformer Performing Differential-to-Single-Ended Conversion

## **Applications Information**

#### **Differential-to-Single-Ended Conversion**

The MAX5854 exhibits excellent dynamic performance to synthesize a wide variety of modulation schemes, including high-order QAM modulation with OFDM.

<u>Figure 7</u> shows a typical application circuit with output transformers performing the required differential-to-single-ended signal conversion. In this configuration, the MAX5854 operates in differential mode, which reduces even-order harmonics, and increases the available output power.

#### **Differential DC-Coupled Configuration**

<u>Figure 8</u> shows the MAX5854 output operating in differential, DC-coupled mode. This configuration can be used in communications systems employing analog quadrature upconverters and requiring a baseband sampling, dual-channel, high-speed DAC for I/Q synthesis. In these

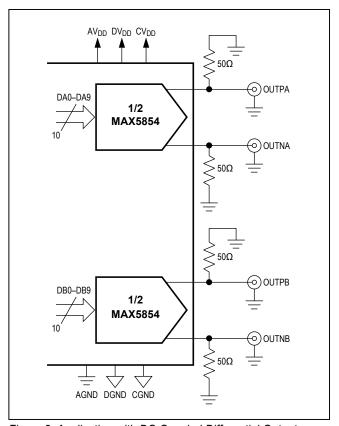


Figure 8. Application with DC-Coupled Differential Outputs

applications, information bandwidth can extend from 10MHz down to several hundred kilohertz. DC-coupling is desirable to eliminate long discharge time constants that are problematic with large, expensive coupling capacitors. Analog quadrature upconverters have a DC commonmode input requirement of typically 0.7V to 1.0V. The MAX5854 differential I/Q outputs can maintain the desired full-scale level at the required 0.7V to 1.0V DC commonmode level when powered from a single 2.85V (±5%) supply. The MAX5854 meets this low-power requirement with minimal reduction in dynamic range while eliminating the need for level-shifting resistor networks.

## Power Supplies, Bypassing, Decoupling, and Layout

Grounding and power-supply decoupling strongly influence the MAX5854 performance. Unwanted digital crosstalk can couple through the input, reference, power-supply, and ground connections, which can affect dynamic specifications, like signal-to-noise ratio or spurious-free dynamic

range. In addition, electromagnetic interference (EMI) can either couple into or be generated by the MAX5854. Observe the grounding and power-supply decoupling guidelines for high-speed, high-frequency applications. Follow the power supply and filter configuration to realize optimum dynamic performance.

Use of a multilayer printed circuit (PC) board with separate ground and power-supply planes is recommended. Run high-speed signals on lines directly above the ground plane. The MAX5854 has separate analog and digital ground buses (AGND, CGND, and DGND, respectively). Provide separate analog, digital, and clock ground sections on the PC board with only one point connecting the three planes. The ground connection points should be located underneath the device and connected to the exposed paddle. Run digital signals above the digital ground plane and analog/clock signals above the analog/clock ground plane. Digital signals should be kept away from sensitive analog, clock, and reference inputs. Keep digital signal paths short and metal trace lengths matched to avoid propagation delay and data skew mismatch.

The MAX5854 includes three separate power-supply inputs: analog (AV<sub>DD</sub>), digital (DV<sub>DD</sub>), and clock (CV<sub>DD</sub>). Use a single linear regulator power source to branch out to three separate power-supply lines (AV<sub>DD</sub>, DV<sub>DD</sub>, CV<sub>DD</sub>) and returns (AGND, DGND, CGND).Filter each power-supply line to the respective return line using LC filters comprising ferrite beads and 10 $\mu$ F capacitors. Filter each supply input locally with 0.1 $\mu$ F ceramic capacitors to the respective return lines.

Note: To maintain the dynamic performance of the *Electrical Characteristics*, ensure the voltage difference between  $DV_{DD}$ ,  $AV_{DD}$ , and  $CV_{DD}$  does not exceed 150mV.

## Thermal Characteristics and Packaging Thermal Resistance

40-lead thin QFN-EP:

$$\theta_{\text{JA}} = 38^{\circ}\text{C/W}$$

The MAX5854 is packaged in a 40-pin thin QFN-EP package, providing greater design flexibility, increased thermal efficiency, and optimized AC performance of the DAC. The EP enables the implementation of grounding techniques, which are necessary to ensure highest performance operation.

In this package, the data converter die is attached to an EP leadframe with the back of this frame exposed at the package bottom surface, facing the PC board side of the package. This allows a solid attachment of the package to the PC board with standard infrared (IR) flow soldering techniques. A specially created land pattern on the PC board, matching the size of the EP (4.1mm x 4.1mm), ensures the proper attachment and grounding of the DAC. Designing vias\* into the land area and implementing large ground planes in the PC board design allows for highest performance operation of the DAC. Use an array of 3 x 3 vias ( $\leq$  0.3mm diameter per via hole and 1.2mm pitch between via holes) for this 40-pin thin QFN-EP package (package code: T4066-1).

# Dynamic Performance Parameter Definitions Adjacent Channel Leakage Ratio (ACLR)

Commonly used in combination with wideband codedivision multiple-access (WCDMA), ACLR reflects the leakage power ratio in dB between the measured power within a channel relative to its adjacent channel. ACLR provides a quantifiable method of determining out-of-band spectral energy and its influence on an adjacent channel when a bandwidth-limited RF signal passes through a nonlinear device.

#### **Total Harmonic Distortion (THD)**

THD is the ratio of the RMS sum of all essential harmonics (within a Nyquist window) of the input signal to the fundamental itself. This can be expressed as:

$$THD = 20 \times log \left[ \frac{\sqrt{\left( {V_2}^2 + {V_3}^2 + {V_4}^2 ... + ... {V_N}^2 \right)}}{V_1} \right]$$

where  $V_1$  is the fundamental amplitude, and  $V_2$  through  $V_N$  are the amplitudes of the 2nd through Nth order harmonics. The MAX5854 uses the first seven harmonics for this calculation.

#### Spurious-Free Dynamic Range (SFDR)

SFDR is the ratio of RMS amplitude of the carrier frequency (maximum signal component) to the RMS value of their next-largest spectral component. SFDR is usually measured in dBc with respect to the carrier frequency amplitude or in dBFS with respect to the DAC's full-scale range. Depending on its test condition, SFDR is observed within a predefined window or to Nyquist.

<sup>\*</sup>Vias connect the land pattern to internal or external copper planes.

#### **Multitone Power Ratio (MTPR)**

A series of equally spaced tones are applied to the DAC with one tone removed from the center of the range. MTPR is defined as the worst-case distortion (usually a 3rd-order harmonic product of the fundamental frequencies), which appears as the largest spur at the frequency of the missing tone in the sequence. This test can be performed with any number of input tones; however, four and eight tones are among the most common test conditions for CDMA- and GSM/EDGE-type applications.

#### Intermodulation Distortion (IMD)

The two-tone IMD is the ratio expressed in dBc of either output tone to the worst 3rd-order (or higher) IMD products.

# Static Performance Parameter Definitions Integral Nonlinearity (INL)

Integral nonlinearity (INL) is the deviation of the values on an actual transfer function from a line drawn between the end points of the transfer function, once offset and gain errors have been nullified. For a DAC, the deviations are measured at every individual step.

#### **Differential Nonlinearity (DNL)**

Differential nonlinearity (DNL) is the difference between an actual step height and the ideal value of 1 LSB. A DNL error specification no more negative than -1 LSB guarantees monotonic transfer function.

#### **Offset Error**

Offset error is the current flowing from positive DAC output when the digital input code is set to zero. Offset error is expressed in LSBs.

#### **Gain Error**

A gain error is the difference between the ideal and the actual full-scale output current on the transfer curve, after nullifying the offset error. This error alters the slope of the transfer function and corresponds to the same percentage error in each step. The ideal current is defined by reference voltage at  $V_{REFO}/I_{RFE} \times 32$ .

#### **Settling Time**

The settling time is the amount of time required from the start of a transition until the DAC output settles to its new output value to within the converter's specified accuracy.

#### Glitch Impulse

A glitch is generated when a DAC switches between two codes. The largest glitch is usually generated around the midscale transition, when the input pattern transitions from 011...111 to 100...000. This occurs due to timing variations between the bits. The glitch impulse is found by integrating the voltage of the glitch at the midscale transition over time. The glitch impulse is usually specified in pV-s.

**Table 4. Part Selection Table** 

PART	SPEED (Msps)	RESOLUTION	
MAX5851	80	8-bit, dual	
MAX5852	165	8-bit, dual	
MAX5853	80	10-bit, dual	
MAX5854	165	10-bit, dual	

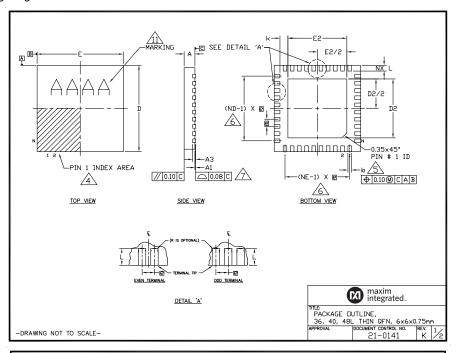
#### **Chip Information**

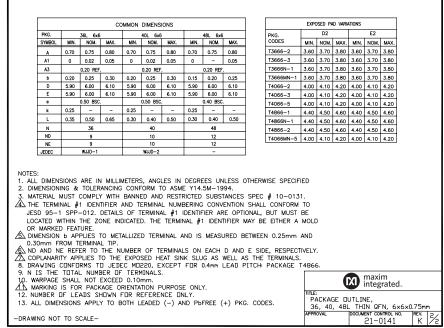
TRANSISTOR COUNT: 9,035

PROCESS: CMOS

#### **Package Information**

For the latest package outline information and land patterns (footprints), go to www.maximintegrated.com/packages. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.





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