# Multimode PA Step-Down Converter with Linear Bypass Mode 


#### Abstract

General Description


The MAX8989 step-down converter is optimized for powering the power amplifier (PA) in multistandard handsets such as LTE, WCDMA, GSM, and EDGE. The device integrates a high-efficiency PWM step-down converter for medium- and low-power transmission with an $85 \mathrm{~m} \Omega$ (typ) low dropout (LDO) bypass regulator, in parallel with the step-down converter, enabling high-power transmission.
The IC uses an analog input driven by an external DAC to control the output voltage linearly for continuous PA power adjustment. The bypass LDO powers the PA directly from the battery during high-power transmission or in case of insufficient headroom between the input and programmed output. The bypass LDO is enabled when the output voltage is greater than 1.0 V . In the case where the output current exceeds the step-down converter current limit, the bypass LDO provides supplementary current to the output, ensuring a stable output voltage. The bypass LDO also provides a smooth transition between step-down regulation and operation in dropout.
The IC is available in a 9 -bump, $1.6 \mathrm{~mm} \times 1.6 \mathrm{~mm}$ WLP package ( 0.69 mm max height).

## Applications

LTE, WCDMA, GSM, and EDGE Cell Phones/ Smartphones

| PART | TEMP RANGE | PIN-PACKAGE |
| :---: | :---: | :---: |
| MAX89889EWL +T | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 9 WLP |
|  | 0.5 mm pitch |  |

+Denotes lead(Pb)-free/RoHS-compliant package.
$T$ = Tape and reel. This device has a minimum order increment of 2500 pieces.

Features

- PA Step-Down Converter
$25 \mu \mathrm{~s}$ (typ) Settling Time for 0.4V to 3.2V Output Voltage Change
Dynamic Output Voltage Setting from 0.4V to Vin
85m $\Omega$ pFET and 100\% Duty Cycle for Low Dropout
2MHz Switching Frequency
Low Output Voltage Ripple
2\% Output Voltage Accuracy Over Load, Line, and Temperature
Tiny External Components
- 2.5A Output Current Capability
- Simple Logic On/Off Control
- Low 0.1 $\mu \mathrm{A}$ Shutdown Current
- 2.7V to 5.5V Supply Voltage Range
- Thermal Overload Protection
- $1.6 \mathrm{~mm} \times 1.6 \mathrm{~mm}$ WLP Package ( 0.69 mm max Height)


## MAX8989

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## ABSOLUTE MAXIMUM RATINGS



| Operating Temperature Range ........................ $40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |  |
| :---: | :---: |
| Junction to Ambient |  |
| Thermal Resistance ( $\theta$ JA) ( Note 2) | $71^{\circ} \mathrm{C} / \mathrm{W}$ |
| Operating Temperature Range | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |
| Junction Temperature (TJMAX) | $+150^{\circ} \mathrm{C}$ |
| Storage Temperature Range. | $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ |
| Soldering Temperature (reflow) | $+260^{\circ} \mathrm{C}$ |

Note 1: LX has internal clamp diodes to PGND and IN1. Applications that forward bias this diode should take care not to exceed the power dissipation limits of the device.
Note 2: Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to www.maximintegrated.com/thermal-tutorial

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## ELECTRICAL CHARACTERISTICS

$\left(\right.$ VIN1 $=$ VIN2 $=$ VSKIP $=$ VEN $=3.6 \mathrm{~V}$, VREFIN $=0.9 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$. Typical values are at $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise noted. ) (Note 3)

| PARAMETER | CONDITIONS |  | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| INPUT SUPPLY |  |  |  |  |  |  |
| Input Voltage Range (VIN) | VIN1 $=$ VIN2 |  | 2.7 |  | 5.5 | V |
| Input Undervoltage Threshold | VIN2 rising, 180mV typical hysteresis |  | 2.52 | 2.63 | 2.70 | V |
| No-Load Supply Current | VEN $=$ VIN_, IOUT $=0 \mathrm{~A}$, SKIP $=$ AGND, switching |  |  | 3 |  |  |
|  | $\mathrm{V}_{\mathrm{EN}}=\mathrm{V}_{\text {IN_, }}, \text { IOUT }=0 \mathrm{~A}, \mathrm{~V}_{\text {SKIP }}=\mathrm{V}_{\text {IN_ }},$ $V_{\text {REFIN }}=0.35 \mathrm{~V}$, no switching |  |  | 0.115 |  | mA |
| Shutdown Supply Current | $V_{E N}=0 V$ | $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$ |  | 0.1 | 1 | $\mu \mathrm{A}$ |
|  |  | $\mathrm{T}_{\mathrm{A}}=+85^{\circ} \mathrm{C}$ |  | 0.1 |  |  |
| THERMAL PROTECTION |  |  |  |  |  |  |
| Thermal Shutdown | TJ rising, $20^{\circ} \mathrm{C}$ typical hysteresis |  |  | +160 |  | ${ }^{\circ} \mathrm{C}$ |
| LOGIC CONTROL |  |  |  |  |  |  |
| EN and SKIP Logic-Input High Voltage |  |  | 1.3 |  |  | V |
| EN and SKIP Logic-Input Low Voltage |  |  |  |  | 0.4 | V |
| EN Internal Pulldown Resistor |  |  |  | 800 |  | k ת |
| SKIP Logic-Input Current | $\mathrm{V}_{\mathrm{IL}}=0 \mathrm{~V}, \mathrm{~V}_{\mathrm{IH}}=5.5 \mathrm{~V}$ | $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$ |  | 0.01 | 1 | $\mu \mathrm{A}$ |
|  |  | $\mathrm{T}_{\mathrm{A}}=+85^{\circ} \mathrm{C}$ |  | 0.1 |  |  |
| POWER-UP TIMING (Figure 2) |  |  |  |  |  |  |
| Time Delay from EN Until LX Starts Switching (tEN_BUCK) |  |  |  | 62 | 130 | $\mu \mathrm{s}$ |

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## ELECTRICAL CHARACTERISTICS (continued)

$\left(V_{I N 1}=V_{I N 2}=V_{S K I P}=V_{E N}=3.6 \mathrm{~V}, V_{\text {REFIN }}=0.9 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}\right.$ to $+85^{\circ} \mathrm{C}$. Typical values are at $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise noted. $)$ (Note 3)


Note 3: The device is $100 \%$ production tested at $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$. Limits over the operating temperature range are guaranteed by design.

## MAX8989

## Multimode PA Step-Down Converter with Linear Bypass Mode

## Typical Operating Characteristics

(Typical Operating Circuit, VIN1 $=$ VIN2 $=3.7 \mathrm{~V}$, VREFIN $=\mathbf{0 . 9 V}$, L1 $=\mathbf{4 . 7 \mu H}$ (TOKO DFE252012C), $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise noted.)


SWITCHING FREQUENCY vs. REFIN VOLTAGE


LOAD REGULATION ERROR vs. LOAD CURRENT


SWITCHING FREQUENCY vs. REFIN VOLTAGE


NO LOAD SUPPLY CURRENT vs. SUPPLY VOLTAGE (SKIP MODE)


LINE REGULATION ERROR
vs. SUPPLY VOLTAGE


SWITCHING FREQUENCY vS. REFIN VOLTAGE


NO LOAD SUPPLY CURRENT vs. SUPPLY VOLTAGE (FPWM MODE)


OUTPUT VOLTAGE ERROR vs. REFIN VOLTAGE


# Multimode PA Step-Down Converter with Linear Bypass Mode 

Typical Operating Characteristics (continued)
(Typical Operating Circuit, VIN1 $=\mathrm{V}_{\mathrm{V}} \mathrm{N} 2=3.7 \mathrm{~V}, \mathrm{~V}$ REFIN $=\mathbf{0 . 9 V}$, L1 $=\mathbf{4 . 7 \mu}$ ( $\mathbf{T O K O}$ DFE252012C), $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise noted.)



EFFICIENCY vs. LOAD CURRENT


EFFICIENCY vs. OUTPUT VOLTAGE


EFFICIENCY vs. LOAD CURRENT


EFFICIENCY vs. LOAD CURRENT


EFFICIENCY vs. OUTPUT VOLTAGE


EFFICIENCY vs. LOAD CURRENT


LIGHT-LOAD SWITCHING WAVEFORMS (SKIP)


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## Multimode PA Step-Down Converter with Linear Bypass Mode

## Typical Operating Characteristics (continued)

(Typical Operating Circuit, $\mathrm{V}_{\mathrm{IN} 1}=\mathrm{V}_{\mathrm{IN} 2}=3.7 \mathrm{~V}, \mathrm{~V}$ REFIN $=\mathbf{0 . 9 V}$, L1 $=\mathbf{4 . 7} \boldsymbol{\mu} \mathbf{H}$ (TOKO DFE252012C), $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise noted.)





# Multimode PA Step-Down Converter with Linear Bypass Mode 

Typical Operating Characteristics (continued)
(Typical Operating Circuit, VIN1 $=\mathrm{V}_{\mathrm{IN} 2}=3.7 \mathrm{~V}, \mathrm{~V}_{\text {REFIN }}=\mathbf{0 . 9 V}$, L1 $=\mathbf{4 . 7 \mu \mathrm { H }}$ ( $\mathbf{T O K O}$ DFE252012C), $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise noted.)


## Multimode PA Step-Down Converter with Linear Bypass Mode

## Typical Operating Characteristics

(Typical Operating Circuit, $\mathrm{V}_{\mathrm{IN} 1}=\mathrm{V} \operatorname{N} 2=3.7 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise noted. PA operating characteristics based on SKY77604 PA Module.)




GSM HIGH-BAND CONVERTER EFFICIENCY vs. OUTPUT POWER


# Multimode PA Step-Down Converter with Linear Bypass Mode 

Typical Operating Characteristics (continued)
(Typical Operating Circuit, $\mathrm{V}_{\mathrm{N} 1}=\mathrm{V}_{\mathrm{I} 2}=3.7 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise noted. PA operating characteristics based on SKY77604 PA Module.)



## Multimode PA Step-Down Converter with Linear Bypass Mode

MAX8989


WLP

Bump Description

| PIN | NAME | FUNCTION |
| :---: | :---: | :---: |
| A1 | AGND | Low-Noise Analog Ground. Connect AGND to the ground plane at a single point away from high switching currents. See the PCB Layout section. |
| A2 | REFIN | Reference Input. REFIN typically connects to the output of an external DAC used to control the IC's output voltage for continuous PA power adjustment. To improve noise immunity, bypass REFIN with a 1000pF capacitor to AGND. The output voltage regulates to $2.0 \times$ VREFIN. REFIN is pulled down to ground through an internal $800 \mathrm{k} \Omega$ resistor. |
| A3 | PGND | Power Ground. Connect PGND to the ground plane near the input and output capacitor grounds. See the PCB Layout section. |
| B1 | EN | Enable Input. Connect EN to IN_ or logic-high for normal operation. Connect EN to ground or logic-low to shut down the output. EN is internally pulled down to ground through an $800 \mathrm{k} \Omega$ resistor. |
| B2 | IN1 | Supply Voltage Input for the Step-Down Converter. Connect IN1 and IN2 to a battery or supply voltage from 2.7V to 5.5 V . Bypass IN1 with a $4.7 \mu \mathrm{~F}$ ceramic capacitor as close as possible between IN1 and PGND. |
| B3 | LX | Inductor Connection |
| C1 | SKIP | Skip Mode Enable Input. Connect SKIP to IN_ or logic-high to enable low-power skip mode during lightload operation when the output voltage is less than 1.0V. Connect SKIP to ground or logic-low for forced PWM operation. |
| C2 | IN2 | Supply Voltage Input for the Bypass LDO. Connect IN1 and IN2 to a battery or supply voltage from 2.7 V to 5.5 V . Bypass IN2 with a $4.7 \mu \mathrm{~F}$ ceramic capacitor as close as possible between IN2 and PGND. |
| C3 | OUT | Output of the Linear Bypass LDO. Connect OUT to the output of the step-down converter. Bypass OUT with four $4.7 \mu \mathrm{~F}$ ceramic capacitors as close as possible to OUT and PGND. |

## Multimode PA Step-Down Converter with Linear Bypass Mode



Figure 1. Functional Diagram
$\square$
Figure 2. Power-Up Timing

# Multimode PA Step-Down Converter with Linear Bypass Mode 

## Detailed Description

The MAX8989 step-down converter is optimized for powering the power amplifier (PA) in multistandard cellular handsets such as LTE, WCDMA, GSM, and EDGE. The IC integrates a high-efficiency PWM step-down converter for medium and low-power transmission with an $85 \mathrm{~m} \Omega$ (typ) bypass regulator, in parallel with the step-down converter, to power the PA during high-power transmission.

## Step-Down Converter

A hysteretic PWM control scheme ensures high efficiency, fast switching, fast transient response, low output ripple, and physically tiny external components. The control scheme is simple: when the output voltage is below the regulation threshold, the error comparator begins a switching cycle by turning on the high-side switch. This high-side switch remains on until the minimum on-time expires and the output voltage is within regulation, or the inductor current is above the currentlimit threshold. Once off, the high-side switch remains off until the minimum off-time expires and the output voltage falls again below the regulation threshold. During the off period, the low-side synchronous rectifier turns on and remains on until the high-side switch turns on again. The internal synchronous rectifier eliminates the need for an external Schottky diode.
Hysteretic control is sometimes referred to as ripple control, since voltage ripple is used to control when the high-side and low-side switches are turned on and off. To ensure stability with low ESR ceramic output capacitors, the IC combines ripple from the output with the ramp signal generated by the switching node (LX). This is seen in Figure 1 with resistor R1 and capacitor C1 providing the combined ripple signal. Injecting ramp voltage from the switching node also improves line regulation because the slope of the ramp adjusts with changes in input voltage.
Hysteretic control has a significant advantage over fixedfrequency control schemes: fast transient response. Hysteretic control uses an error comparator, instead of an error amplifier with compensation, and there is no fixed-frequency clock. Therefore, a hysteretic converter reacts virtually immediately to any load transient on the output without having to wait for a new clock pulse or for the output of the error amplifier to move as with a fixedfrequency converter.

With a fixed-frequency step-down converter, the magnitude of output voltage ripple is a function of the switching frequency, inductor value, output capacitor and ESR, and input and output voltage. Since the inductance value and switching frequency are fixed, the output ripple varies with changes in line voltage. With a hysteretic stepdown converter, since the ripple voltage is essentially fixed, the switching frequency varies with changes in line voltage. Some variation with load current can also be seen, however, this is part of what gives the hysteretic converter its great transient response.
The IC is trimmed to provide a 2 MHz switching frequency during $50 \%$ duty cycle condition (3.6V input and 1.8 V output). See the Typical Operating Characteristics section for more information on how switching frequency can vary with respect to load current and supply voltage.

## Voltage-Positioning Load Regulation

The IC step-down converter utilizes a unique feedback network. By taking DC feedback from the LX node through R1 of Figure 1, the usual phase lag due to the output capacitor is removed, making the loop exceedingly stable and allowing the use of very small ceramic output capacitors. To improve the load regulation, resistor R3 is included in the feedback. This configuration yields load regulation equal to half of the inductor's series resistance multiplied by the load current. This voltage-positioning load regulation greatly reduces overshoot during load transients and when changing the output voltage from one level to another. However, when calculating the required REFIN voltage, the load regulation should be considered. Because inductor resistance $\left(R_{L}\right)$ is typically well specified and the typical PA is a resistive load, the VREFIN to VOUT gain is slightly less than $2.0 \mathrm{~V} / \mathrm{V}$. The output voltage is approximately:

$$
V_{\text {OUT }}=2 \times V_{\text {REFIN }}-\frac{1}{2} \times R_{\text {L }} \times I_{\text {LOAD }}
$$

When the output voltage drops by more than 60 mV (typ) due to load regulation ( $0.5 \times R \mathrm{~L} \times \operatorname{lLOAD}>60 \mathrm{mV}$ ) and the output voltage is above the linear bypass threshold (1V typ), the linear bypass regulator starts to supplement current to the output ensuring that the output is kept in regulation. While the linear bypass regulator is sourcing current, the step-down converter continues to supply most of the load to maximize efficiency.

# Multimode PA Step-Down Converter with Linear Bypass Mode 


#### Abstract

Skip Mode The IC has an optional skip mode that provides the highest possible efficiency during light load conditions. Skip mode is active when SKIP is logic-high and VOUT is less than 1 V . In addition, when the bypass LDO is sourcing current, skip mode is automatically enabled to prevent the stepdown converter from sinking current in an overvoltage condition. During skip mode, the hysteretic comparator turns on the high-side switch based on the output voltage value. Once the output voltage is high enough, the high-side switch is turned off and the low-side switch is turned on to return the inductor current to zero. A zero-crossing comparator is enabled in this mode to minimize power consumption by turning off the low-side switch as close as possible to the true inductor-current zero-crossing. In skip mode, the output ripple remains low at all loads, and the switching frequency decreases with lighter loads.


## Linear Bypass and Dropout

A low-dropout linear regulator is connected in parallel with the step-down converter. The output voltage of the linear regulator is set slightly lower than the nominal regulation voltage of the step-down converter $(60 \mathrm{mV}$ typ). This allows the output to maintain regulation when the output is slewed at a rate faster than the bandwidth of the step-down converter and when the load current exceeds the current limit of the step-down converter. Linear bypass operation is disabled when the output voltage is below the linear bypass regulation enable threshold (1V typ).
The IC enters full dropout under two conditions:

- The IC is commanded to regulate to a setting higher than VIN.
- REFIN is set to more than 2.1V (min).

Under either condition, the step-down converter goes to $100 \%$ duty cycle by turning on its p-channel MOSFET, and the linear regulator enters dropout by turning on fully. Note that forced dropout mode (the second condition) does not implement hysteresis on REFIN.

## Shutdown

Connect EN to ground or logic-low to place the IC in shutdown mode, reducing the input current to $0.1 \mu \mathrm{~A}$ (typ). In shutdown, the control circuitry, bypass linear regulator, internal switching MOSFET, and synchronous rectifier turn off, and LX becomes high impedance. Connect EN to IN_ or logic-high for normal operation.

## Thermal Overload Protection

Thermal overload protection limits total power dissipation in the IC. If the junction temperature exceeds $+160^{\circ} \mathrm{C}$, the IC turns off, allowing it to cool. The IC turns on and begins soft-start after the junction temperature cools by $20^{\circ} \mathrm{C}$. This results in a pulsed output during continuous thermal-overload conditions.

## Applications Information

## Inductor Selection

The step-down converter operates with a typical switching frequency of 2 MHz . A $4.7 \mu \mathrm{H}$ is recommended for best performance. The inductor's DC current rating only needs to match the maximum load of the application because the IC features zero-current overshoot during startup and load transients. See Table 1 for suggested inductors and manufacturers.

## Output Capacitor Selection

The output capacitor keeps the output voltage ripple small and ensures regulation loop stability. Cout must have low impedance at the switching frequency. Ceramic capacitors with X5R or X7R temperature characteristics are highly recommended due to their small size, low ESR, and small temperature coefficients. Note that some ceramic dielectrics exhibit large capacitance and ESR variation with temperature and DC bias. Ceramic capacitors with Z5U or Y5V temperature characteristics should be avoided. Tantalum capacitors are not recommended.
Four $4.7 \mu \mathrm{~F}$ output capacitors are recommended for most applications. For optimum load-transient performance and very low output ripple, the output capacitor value can be increased, however, care should be taken with regards to output voltage slew rate requirements.

## Input Capacitor Selection

The input capacitors reduce the current peaks drawn from the battery or input power source and reduce switching noise in the IC. The impedance of CIN1 and CIN2 at the switching frequency should be kept very low. Ceramic capacitors with X5R or X7R temperature characteristics are highly recommended due to their small size, low ESR, and small temperature coefficients. Note that some ceramic dielectrics exhibit large capacitance and ESR variation with temperature and DC bias. Ceramic capacitors with $\mathrm{Z5U}$ or Y 5 V temperature characteristics should be avoided.
For most applications, connect a $4.7 \mu \mathrm{~F}$ capacitor from IN1 to PGND and a $4.7 \mu \mathrm{~F}$ capacitor from IN2 to PGND. For optimum noise immunity and low input ripple, the input capacitor value can be increased.

## Multimode PA Step-Down Converter with Linear Bypass Mode

## Table 1. Suggested Inductors

| MANUFACTURER | SERIES | INDUCTANCE <br> $(\boldsymbol{\mu H})$ | $\mathbf{R L}$ <br> $(\mathbf{m} \boldsymbol{\Omega} \boldsymbol{t y p})$ | CURRENT RATING <br> $(\mathbf{m A})$ | DIMENSIONS <br> $(\mathbf{m m} \mathbf{m a x})$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | DEM2810C | 4.7 | 170 | 1000 | $3.0 \times 3.2 \times 1.0$ |
|  | DFE252010C | 4.7 | 320 | 1600 | $2.7 \times 2.2 \times 1.0$ |
|  | DFE252012C | 4.7 | 210 | 1600 | $2.7 \times 2.2 \times 1.2$ |
| TDK | VLF302510 | 4.7 | 140 | 950 | $3.0 \times 2.5 \times 1.0$ |
|  | VLS252010T | 4.7 | 367 | 980 | $2.6 \times 2.1 \times 1.0$ |
| Samsung | CIG22H4R7MNE | 4.7 | 233 | 1000 | $2.7 \times 2.2 \times 1.2$ |

## Thermal Considerations

In applications where the IC runs at high ambient temperatures or with heavy loads, the heat dissipated may exceed the maximum junction temperature of the part. If the junction temperature reaches approximately $+160^{\circ} \mathrm{C}$, the thermal overload protection is activated.
The IC maximum power dissipation depends on the thermal resistance of the package and circuit board, the temperature difference between the die junction and ambient air, and the rate of airflow. The maximum allowed power dissipation is:

$$
\text { PMAX }=\left(T J M A X-T_{A}\right) / \theta_{J A}
$$

where $T_{A}$ is the ambient temperature, TJmax is the maximum junction temperature, and $\theta \mathrm{JA}$ is the junction to ambient thermal resistance. See the Absolute Maximum Ratings section.
The power dissipated in the device is approximately

$$
P_{D}=V_{O U T} \times I_{\text {LOAD }} \times\left(\frac{1}{\eta}-1\right)-\left(I_{L}^{2} \times R_{L}\right)
$$

where $\eta$ is the efficiency of the MAX8989 (see the Typical Operating Characteristics section), ILOAD is the RMS load current, IL is the RMS inductor current, and $\mathrm{RL}_{\mathrm{L}}$ is the inductor resistance.

PCB Layout
High switching frequencies and relatively large peak currents make the PCB layout a very important part of design. Good design minimizes excessive EMI on the feedback paths and voltage gradients in the ground plane, resulting in a stable and well-regulated output.
For the input supplies, it is critical to route them as separate lines from the power source with separate decoupling capacitors on IN1 and IN2. This is necessary to prevent switching noise on IN1 from coupling into IN2.

Grounding of the IC is also critical. The AGND and PGND must be routed as separate nets, and connected together as close as possible to the PGND bump of the IC. AGND can be used to shield REFIN along its routing. AGND must be connected to the ground of the source generating REFIN. To avoid noise coupling into AGND, care must be taken in the layout to ensure isolation from AGND to PGND, having cuts in the ground plane wherever necessary.
The input decoupling capacitor on IN1 filters the input supply of the step-down converter. The layout needs to ensure as short a path as possible from IN1, through CIN1, to PGND for optimal decoupling. The point in the layout where this input capacitor connects to PGND serves as the star-connection ground point for all three critical capacitors (CIN1, CIN2, and Cout).

The input decoupling capacitor on IN2 filters the input supply for the linear regulator. Its bottom plate should be routed to the star-ground point in the layout.

The OUT trace needs to be short and wide because it carries the current from the linear regulator.
The trace between the inductor and LX should also be low impedance as this trace has a noisy, switching waveform. Keep LX away from noise-sensitive traces such as REFIN and AGND.
The capacitor from REFIN to AGND is optional. The REFIN capacitor can be used when needed to prevent high-frequency noise from coupling into REFIN.
The ground connection among CIN, COUT, and the PA ground is also extremely critical. Parasitic impedance in this ground connection results in degraded RF performance. Contact your Maxim representative for more detailed information and assistance.

For a PCB layout example, refer to the MAX8989 Evaluation Kit data sheet.

# Multimode PA Step-Down Converter with Linear Bypass Mode 

For the latest package outline information and land patterns, go to www.maximintegrated.com/packages. Note that a "+", "\#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

| PACKAGE <br> TYPE | PACKAGE <br> CODE | OUTLINE <br> NO. | LAND <br> PATTERN NO. |
| :---: | :---: | :---: | :---: |
| 9 WLP | W91B1+1 | $\underline{21-0067}$ | Refer to <br> Application <br> Note 1891 |

## MAX8989

## Multimode PA Step-Down Converter <br> with Linear Bypass Mode

| REVISION <br> NUMBER | REVISION <br> DATE | DESCRIPTION | PAGES <br> CHANGED |
| :---: | :---: | :--- | :---: |
| 0 | $11 / 10$ | Initial release | - |
| 1 | $1 / 11$ | Updated IN1, IN2, OUT, LX current absolute maximum rating | 2 |

